Tractable Reliable Broadcast with honest dealer in Multihop Networks

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Target System Model





Problem Statement: Byzantine Reliable Broadcast with honest dealer

A *correct* process *s* called *source* wants to send a message to all other processes, ensuring:

- Safety: if a correct process delivers a message m then it has been previously sent by the source;
- Liveness: if a correct process broadcasts a message m, then m will be eventually delivered by every correct process.

Failure Assumptions

Globally Bounded







f=1

Specific Spatial Distribution, Probabilistic Distribution, etc.

f=1

up to *f* faulty processes arbitrarily spread over the system up to f faulty processes in the neighborhood of every process

Simplest solution: Digital Signatures

Reliable Authenticated Channels

- Reliable Delivery;
- ► No creation;
- ► Authenticity.



Static Multi-hop Network, assuming at most f faulty processes, Safety + Liveness \iff Network connectivity greater than 2f

D. Dolev. "Unanimity in an unknown and unreliable environment." Foundations of Computer Science, 1981. SFCS'81. 22nd Annual Symposium on. IEEE, 1981.

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Known Topology

Unknown Topology

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Known Topology

Unknown Topology

- Messages are routed through multiple fixed disjoint routes;
- Delivery Complexity: polynomial;
- Message Complexity: polynomial;

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Known Topology

- Messages are routed through multiple fixed disjoint routes;
- Delivery Complexity: polynomial;
- Message Complexity: polynomial;

Unknown Topology

- Message flooding, the IDs of the traversed nodes are collected;
- Delivery Complexity: NP-Complete;
- Message Complexity: factorial;

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- Globally Bounded Failure Model
- Reliable Authenticated Channels
- Topology Unaware
- \implies Delivery Complexity:
- NP-Complete;
- \implies Message Complexity: factorial;

ls it possible to do better? We revised and improved the protocol proposed by Dolev

System Model:

- n processes (each one with an unique identifier);
- static communication network;
- messages exchange;
- processes: correct or Byzantine faulty;
- globally bounded faults: up to f processes can be Byzantine faulty;
- processes have no global knowledge (except the value of f);
- synchronous system;
- reliable authenticated channels.



f = 1, msg := $\langle source, content, path \rangle$



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Propagation algorithm: a process saves and relays msg sent by a neighbor q to all neighbors not included in *paths*, appending to it the id of the sender q.



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Verification algorithm: if a process receives many *msg* carrying the same *source* and *content* and it is possible to identify f + 1 disjoint paths among the related *paths*, then *content* is delivered by the process.



The propagation algorithm always generates **one message for every path** interconnecting the source with another node \implies **factorial** messages in the size of the network;

Deliver the contents directly sent from the source.



Safety: if a correct process delivers a message *m* then it has been previously sent by the source;

Reliable Authenticated Channel: No creation, Authenticity;

The delivered content can be relayed with an empty path.



A delivered content has been verified enforcing safety.

 Relay further paths only to the neighbors that have not yet delivered.



 \bowtie do not increase the number of disjoint paths computed on r.

Stop relaying further paths once the empty path has relayed (= halting condition).



 \bowtie do not increase the number of disjoint paths computed on r.

If a neighbor q has delivered, then discard any further path that contains the label of q.



 \bowtie do not increase the number of disjoint paths computed on r.















Preventing Flooding and Forwarding Policy

Every process has to consider all the received paths to deliver a content

 \Rightarrow a Byzantine process can flood the correct processes with spurious paths \Rightarrow No Liveness

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 Bound the channel capacity (i.e. constrain the number of messages that can be sent in a time window)

 \Rightarrow Forwarding Policy (which messages to send?)

 \Rightarrow **Multi-Shortest** Policy (i.e. give priority to "useful" shorter paths)

Protocol Evaluation: Simulation Setting

- synchronous system that evolves in sequential synchronous rounds;
- $f = \lfloor (k-1)/2 \rfloor$ passive and active Byzantines;
- unbounded and bounded channel capacity (bound = f + 1);
- different topologies: random regular, k-pasted-tree, k-diamond, multi-partite wheel, Barabási-Albert graph, generalized wheel;



(a) multipartite wheel (b) generalized wheel(c) k-pasted-tree (d) k-diamond

Comparison with the state of art



unbounded channel capacity, random regular graph, 5-connected networks.

Message Complexity



n=200, $f = \lfloor (k-1)/2 \rfloor$, bounded channels (a) passive Byzantines (b) active Byzantines.

Broadcast Latency



n=200, $f = \lfloor (k-1)/2 \rfloor$, bounded channels (a) passive Byzantines (b) active Byzantines.

Forwarding Policy Delay



n = 100, $f = \lfloor (k - 1)/2 \rfloor$, passive Byzantine (a) bounded channel & Multi-Shortest policy (b) unbounded channels.

Barabási-Albert graph



message complexity, $f = \lfloor (k-1)/2 \rfloor$, bounded channels, n = 100, 150, 200(a) passive Byzantines, (b) active Byzantines.

Barabási-Albert graph



broadcast latency, $f = \lfloor (k-1)/2 \rfloor$, bounded channels, n = 100, 150, 200(a) passive Byzantines, (b) active Byzantines.

Generalized Wheel



 $f = \lfloor (k-1)/2 \rfloor$, bounded channels, n = 100(a) message complexity, (b) broadcast latency.

Comments

The protocol we defined **works also on asynchronous** systems and can be ported on **dynamic networks**

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but some additional assumptions have to be considered on order to keep it practically employable



Failure Assumptions

Globally Bounded







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up to *f* faulty processes arbitrarily spread over the system up to f faulty processes in the neighborhood of every process

Static Multi-hop Network

Assuming at most f faulty processes in the neighborhood of every node

¹Pagourtzis, Aris, Giorgos Panagiotakos, and Dimitris Sakavalas. "Reliable broadcast with respect to topology knowledge." Distributed Computing 30.2 (2017): 87-102.

Static Multi-hop Network

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Known Topology ¹

Unknown Topology

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Static Multi-hop Network

Assuming at most f faulty processes in the neighborhood of every node

Known Topology ¹

 Tollerate more faulty process with respect unknown topology;

 Delivery Complexity: NP-Hard;

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Unknown Topology

Static Multi-hop Network

Assuming at most f faulty processes in the neighborhood of every node

Known Topology ¹

- Tollerate more faulty process with respect unknown topology;
- Delivery Complexity: NP-Hard;

Unknown Topology

- Delivery Complexity: constant
- Message Complexity: polynomial;

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Certified Propagation Algorithm (CPA)



f = 1

- the source broadcasts the message;
- a neighbor of the source directly accepts and relays the message;
- a process that receives the same message from f + 1 distinct neighbors accepts and relays the message.

A. Pelc, D. Peleg. "Broadcasting with locally bounded byzantine faults". Information Processing Letters 93(3), 109-115 (2005)


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Necessary and Sufficient conditions²

Necessary condition: MKLO with k = f+1

Sufficient condition: MKLO with k = 2f+1

Strict condition: MKLO with k = f+1 removing any possible placement of the Byzantine processes (NP-Complete Problem)

²Chris Litsas, Aris Pagourtzis, and Dimitris Sakavalas. "A graph parameter that matches the resilience of the certified propagation algorithm." International Conference on Ad-Hoc Networks and Wireless. Springer, Berlin, Heidelberg, 2013.









G1

The order of the appearances matters

System Model:

- n processes (each one with an unique identifier);
- dynamic communication network evolving graph;
- messages exchange;
- processes: correct or Byzantine faulty;
- *locally bounded faults*: up to *f* processes can be Byzantine faulty in the neighborhood of every process;
- processes have no global knowledge (except the value of f);

synchronous system;

reliable authenticated channels.

The CPA protocol can easily be ported on dynamic networks

 \rightarrow every process has to relay delivered messages to every new process met.

CPA liveness on dynamic networks

Temporal Minimum K-Level Ordering (TMKLO)

TMKLO is a partition of V in levels L_i , each one with a time i associated.

Necessary condition: TMKLO with k = f + 1

Sufficient condition: TMKLO with k = 2f + 1

Comments

It is possible to verify whether the reliable broadcast can be achieved

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but the precise characterization about the evolution of the network has to be provided (i.e. all the snapshots)

or classes of dynamic networks in which there exist a specific subgraph in which the edges reappear infinitively often.

Conclusion and open issues 1

 reliable broadcast with honest dealer on static multi-hop network, globally bounded failure model, polynomial message complexity

 \Rightarrow prove a theoretical bound for the message complexity

 \Rightarrow it may help in identifying conditions from a polynomial message complexity on dynamic networks

 \Rightarrow weaker safety and/or liveness properties

 \Rightarrow tractable self-stabilizing broadcast in dynamic networks (arbitrary initial state of processes and channels)

Conclusion and open issues 2

 conditions for reliable broadcast with honest dealer on dynamic multi-hop network, locally bounded failure model

but, dynamic networks are usually characterized by global and general features

 \Rightarrow conditions on the dynamic networks that guarantee the liveness of reliable broadcast without the precise knowledge of the evolution?

 \Rightarrow weaker safety and/or liveness properties

 \Rightarrow tractable self-stabilizing broadcast (arbitrary initial state of processes and channels)

References

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