

# PADEC

## A Framework for Certified Self-Stabilization

Karine Altisen, Pierre Corbineau, Stéphane Devismes,

Univ. Grenoble Alpes, CNRS, Grenoble INP<sup>1</sup>, VERIMAG, 38000 Grenoble, France

October, 2017



---

<sup>1</sup>Institute of Engineering Univ. Grenoble Alpes

# Proving Self-stabilization

From [Lamport, 2012],

*"proofs are still written in prose pretty much the way they were in the 17<sup>th</sup> century. [...]"*

*"proofs are unnecessarily hard to understand, and they encourage sloppiness that leads to errors."*

More complex

- ▶ Algorithms
- ▶ Topologies,
- ▶ Scheduling assumptions
- ▶ ...

⇒ **Transition to automated proof-checking**

# The Coq Proof Assistant

- ▶ Functional language for definitions
- ▶ Interactive proof-editing
- ▶ Automated proof-checking



Coq has received the **ACM Software System 2013 award**.

## *Example Applications:*

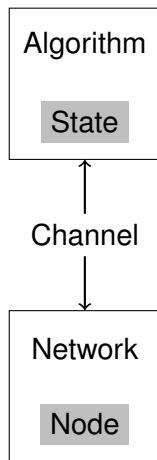
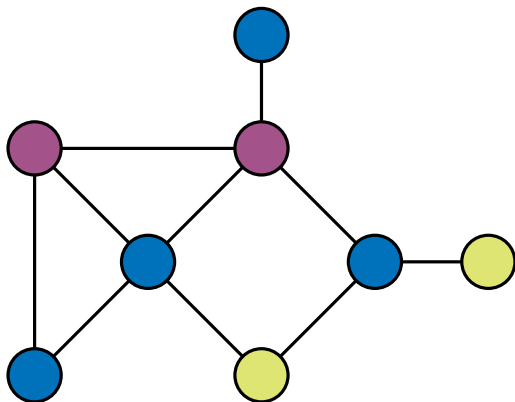
- ▶ System proofs
  - ▶ CompCert certified C compiler [X.Leroy *et al.*]
- ▶ Mathematical proofs
  - ▶ Four-color theorem [G. Gonthier *et al.*]

«*Preuves d'Algorithmes Distribués En Coq*»  
"Proofs of Distributed Algorithms with Coq"

- ▶ **Goal:** Formal proofs for distributed *self-stabilizing* algorithms.
- ▶ **Formalism:** Coq and its libraries as a foundation
- ▶ **PADEC provides a Coq library including:**
  - ▶ Computational Model
  - ▶ Lemmas corresponding to common proof patterns.
  - ▶ Case-studies.

# Distributed System

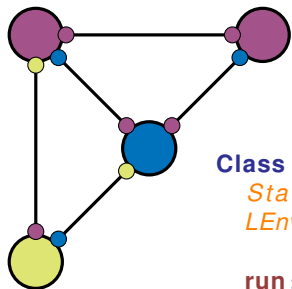
Distributed System = *Network* + *Algorithm*  
both communicate via *Channel*



# Network and Topology

```
Class Network (Channel: Type): Type := mkNet {  
  Node: Type;  
  peer: Node → Channel → Node ∪ { ⊥ };  
  is_channel n1 c12 n2 := (peer n1 c12) = (Some n2);  
  
  peers: Node → list Channel;  
  peers_spec: ∀ n1 c12,  
    (c12 ∈ peers n1) ⇔ ∃ n2, (is_channel n1 c12 n2);  
  
   $\rho$ : Node → Channel → Channel;  
   $\rho$ _spec: ∀ n1 n2 c12 c21,  
    (is_channel n1 c12 n2 ∧ is_channel n2 c21 n1)  
    → ( $\rho$  n1 c12) = c21;  
  
  all_nodes: list Node;  
  all_nodes_prop: ∀ n, n ∈ all_nodes  
}.
```

# Locally Shared Memory Model



```
Class Algorithm (Channel:Type) := mkAlgo {  
  State: Type;  
  LEnv := Channel → State ∪ { ⊥ };  
  
  run: list Channel → (Channel → Channel)  
    → State → LEnv → State ∪ { ⊥ };  
  
  (*use: (run peers ρ state neigh_states) *)  
  
  ROState: Type; RO_part: State → ROState;  
  RO_stable: (* ROState cannot be overwritten *)  
    ...  
}
```

# Functional Representation of Algorithm

Operational Representation

Variables:

$n \in \mathbb{N}$

...

Actions:

Guard<sub>1</sub> → Assign<sub>1</sub>

Guard<sub>2</sub> → Assign<sub>2</sub>

...

Functional Representation

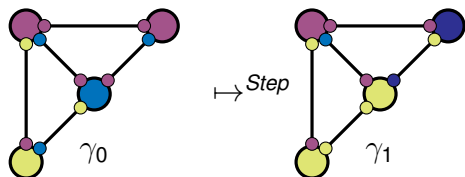
```
Record state := mkState {  
  n: nat;  
  ...  
}.
```

```
run peers  $\rho$  s  $\ell$  :=
```

```
  Assign_1 s if (Guard_1 s  $\ell$ )  
else Assign_2 s if (Guard_2 s  $\ell$ )  
  
else ...  
  
else  $\perp$ 
```



# Relational Semantics



**Configuration** (the state of every node):

$\gamma_0 : Env$

$Env := Node \rightarrow State$

**Step of execution**  $Step \gamma_1 \gamma_0$

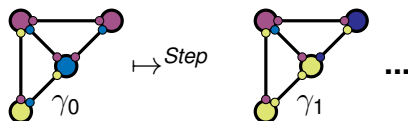
$Step : Env \rightarrow Env \rightarrow Prop$

For all node  $n$ ,

- ▶  $\gamma_1(n) = \gamma_0(n)$  OR
- ▶ `run` returns a state  $s'$  and  $\gamma_1(n) = s'$

$\gamma_0 \langle \rangle \gamma_1$

# Relational Semantics (2)



**Execution:**  $e = \gamma_0 \mapsto^{Step} \gamma_1 \mapsto \dots$   
 $e = \gamma_0 \mapsto^{Step} \gamma_1 \mapsto^{Step} \dots \gamma_T$  ( $\gamma_T$  is *terminal*)

$is\_exec\ e$

$is\_exec: Exec \rightarrow Prop$

**Coinductive *Exec*: Type :=**

| e\_one:  $Env \rightarrow Exec$  | e\_cons:  $Env \rightarrow Exec \rightarrow Exec$ .

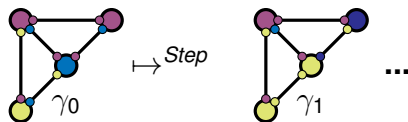
**Coinductive  $is\_exec: Exec \rightarrow Prop :=$**

| i\_one:  $\forall (g: Env), terminal\ g \rightarrow is\_exec\ (e\_one\ g)$

| i\_cons:  $\forall (e: Exec) (g: Env),$

$is\_exec\ e \rightarrow Step\ g\ (Fst\ e) \rightarrow is\_exec\ (e\_cons\ g\ e)$ .

# Relational Semantics (3)



## Daemon

- ▶ No more constraint  $\rightarrow$  **Unfair Daemon**
- ▶ **Weakly Fair Daemon:** every enabled node is eventually executed (or neutralized)

`weakly_fair e`

`weakly_fair: Exec  $\rightarrow$  Prop`

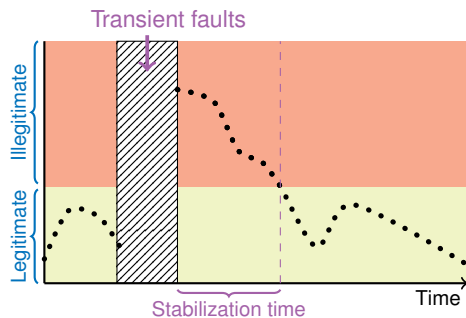
```
weakly_fair e :=  $\forall$  (n: Node),  
  Always (fun e' => enabled n e'  
     $\rightarrow$  Eventually (act_neut n) e') e.
```

# Eventually / Always Operators

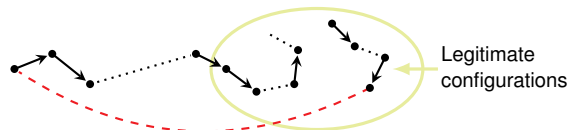
**Inductive** Eventually (P: Exec → Prop): Exec → Prop :=  
| eventually\_now: ∀ e, P e → Eventually P e  
| eventually\_later: ∀ g e, Eventually P e →  
Eventually P (e\_cons g e).

**CoInductive** Always (P: Exec → Prop): Exec → Prop :=  
| always\_one: ∀ g, P (e\_one g) → Always P (e\_one g)  
| always\_cons: ∀ g e, P (e\_cons g e) →  
Always P e → Always P (s\_cons g e).

## Self-Stabilization



- ▶ Convergence
- ▶ Closure
- ▶ Spec. ok



# Specification (2)

**closure**  $\mathcal{L} := \forall \gamma \gamma',$   
Assume\_RO  $\gamma \rightarrow \gamma \in \mathcal{L} \rightarrow \text{Step } \gamma' \gamma \rightarrow \gamma' \in \mathcal{L} .$

**convergence**  $\mathcal{L} := \forall e,$   
Assume\_RO  $(\text{Fst } e) \rightarrow \text{is\_exec } e \rightarrow$   
Eventually  $(\text{fun } e \Rightarrow (\text{Fst } e) \in \mathcal{L}) e .$

**spec\_ok**  $\mathcal{L} \text{ } SP := \forall e,$   
Assume\_RO  $(\text{Fst } e) \rightarrow \text{is\_exec } e \rightarrow (\text{Fst } e) \in \mathcal{L} \rightarrow SP e .$

**self\_stab**  $SP := \exists \mathcal{L},$   
**closure**  $\mathcal{L} \wedge$  **convergence**  $\mathcal{L} \wedge$  **spec\_ok**  $\mathcal{L} \text{ } SP .$

## Competitive self-stabilizing $k$ -clustering

Datta, A.K., Larmore, L.L., Devismes, S., Heurtefeux, K., Rivierre, Y., TCS (2016)

Self-stabilizing algorithm for  $k$ -clustering, from rooted spanning tree

- ▶ 3-rule algorithm
- ▶ Proof of convergence + closure + spec. ok
- ▶ + Quantitative guarantee: bound on the number of clusters

# Tools for Convergence

→ Use a potential function  $Pot$  on configurations and a well-founded order  $<_{st}$ :

$$\forall \gamma_1 \gamma_2, \text{Step } \gamma_2 \gamma_1 \rightarrow Pot\gamma_2 <_{st} Pot\gamma_1$$

Usually: aggregating local potential values at all nodes

- ▶ Sum of potentials at all nodes (integer values)
- ▶ Multiset of potentials at all nodes (arbitrary ordered values)



## Tools for Convergence (2)

**Finite Multiset ordering:** To obtain  $M_1$  smaller than  $M_2$

- ▶ remove some copies of big values from  $M_2$
- ▶ replace them with any number of smaller values in  $M_1$

This finite multiset ordering is *well-founded*,  
(provided that the value ordering relation is well-founded)

[Dershowitz, Manna 1979]

Coq proof: [CoLoR Library, 2011]

**Simplified criteria:** during a step,

- ▶ potential must change at some node **and**
- ▶ when a node increases its potential,  
there must be another node with higher potential whose  
potential decreases  
(alibi/scapegoat node)

# Quantitative Properties

- ▶ Comparison of arbitrary set cardinalities
  - ▶ Witnessed by an injective functional relation between elements
- ▶ Counting of elements by comparison to  $\{0, \dots, n - 1\}$
- ▶ Effect of set-theoretic operators on cardinality:
  - ▶ intersection, union, product,
  - ▶ set comprehension, inclusion
  - ▶ singleton, empty set
  - ▶ logical operators on comprehension predicates

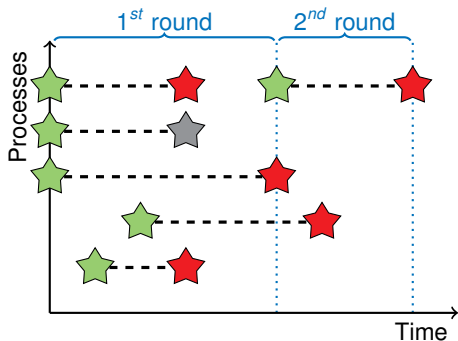
# Work in progress

## Non silent algorithms

- ▶ Express and prove fairness properties,
- ▶ Token circulation

## Complexity

- ▶ Steps
- ▶ Rounds



Thank you!

## Any Question?

### **PADEC website:**

<http://www-verimag.imag.fr/~altisen/PADEC/>

### *A Framework for Certified Self-Stabilization.*

Karine Altisen, Pierre Corbineau, Stéphane Devismes

Logical Methods in Computer Science

(special issue of FORTE 2016)

(To appear)