Set-Constrained Delivery Broadcast: Definition, Abstraction Power, and Computability Limits

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Descartes Seminar

October 1st, 2018

From a paper published at ICDCN 2018





Introduction – Equivalence Broadcast/Objects

Hypothesis on the system



Introduction - Outline

- 1. Introduction
- 2. Consistency
- 3. Definition of SCD-Broadcast
 - Intuition Definition Properties
- 4. Abstraction Power

Sequentially consistent grow-only set Atomic grow-only set Sequentially consistent snapshot object Atomic snapshot object

5. Implementation and Computability Limits

Computability limits Message-passing implementation Complexity

6. Perspectives

Consistency – Which histories are correct?





Sequentially consistent:



Causally consistent:



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Consistency - Which histories are correct?





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Causally consistent:



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Consistency - Which histories are correct?





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◆□ → ◆圖 → ◆ 国 → ◆ 国 → ○

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Causally consistent:



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Consistency – Which histories are correct?





Sequentially consistent:



Causally consistent:



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Consistency - Sequential consistency

An execution is sequentially consistent if

There is a total order on all operations such that:

- The order is compliant with the order of each process
- The sequential specification is respected

Counter-example



Example



Consistency - Linearizability

An execution is linearizable if

Same as sequential consistency, and:

▶ The order is compliant with real-time

Counter-example



Example



Grow-only set (G-Set) object: operations insert(v): adds $v \in \mathbb{N}$ to the set read(): returns the full set

Algorithm with Atomic Broadcast

- 1 operation read(): return state;
- 2 **operation** *insert*(v): atomic-broadcast (I(v)); wait delivery;
- 3 **event** atomic-deliver(I(v)): state \leftarrow state $\cup \{v\}$;



Grow-only set (G-Set) object: operations insert(v): adds $v \in \mathbb{N}$ to the set read(): returns the full set

Algorithm with FIFO Broadcast

- 1 operation read(): return state;
- **2** operation *insert*(v): fifo-broadcast (I(v)); wait delivery;
- 3 **event** fifo-deliver(I(v)): state \leftarrow state $\cup \{v\}$;



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Grow-only set (G-Set) object: operations insert(v): adds $v \in \mathbb{N}$ to the set read(): returns the full set

Algorithm with SCD Broadcast

- 1 operation read(): return state;
- 2 **operation** *insert*(v): scd-broadcast (I(v)); wait delivery;
- 3 **event** scd-deliver({ $I(v_1), ..., I(v_k)$ }): state \leftarrow state \cup { $v_1, ..., v_k$ };



Definition – Set-Constraint Delivery Broadcast

Interface

operation: scd-broadcast (m)

event: scd-deliver (mset)

Properties

Definition – Set-Constraint Delivery Broadcast

Interface

operation: scd-broadcast (m) event: scd-deliver (mset)

Properties

Validity: p_i scd-delivers $m \in mset \Rightarrow$ some p_j scd-broadcast mIntegrity: m is scd-delivered at most once by p_i

MS-Ordering: p_i scd-delivers $m \in mset_i$ and later $m' \in mset'_i$ \Downarrow

impossible that

 p_j scd-delivers $m' \in \textit{mset}'_i$ and later $m \in \textit{mset}_j$

Termination-1: If a non-faulty p_i scd-broadcasts m, it terminates its scd-broadcast invocation and scd-delivers $m \in mset$

Termination-2: *pi* scd-delivers *m*

 \Rightarrow every non-faulty p_j scd-delivers $m \in mset$

Definition - Set-Constraint Delivery Broadcast

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Messages SCD-broadcast by processes:

 $m_1, m_2, m_3, m_4, m_5, m_6, m_7, m_8$

Correct SCD-deliveries

at
$$p_1$$
: $\{m_1, m_2\}$, $\{m_3, m_4, m_5\}$, $\{m_6\}$, $\{m_7, m_8\}$
at p_2 : $\{m_1\}$, $\{m_2, m_3\}$, $\{m_4, m_5, m_6\}$, $\{m_7\}$, $\{m_8\}$
at p_3 : $\{m_1, m_2, m_3\}$, $\{m_4, m_5, m_6\}$, $\{m_7\}$, $\{m_8\}$

Incorrect SCD-deliveries

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Definition - Propositions

Graph interpretation

► Local SCD-delivery order: $m \mapsto_i m'$

- *p_i* delivers *m* in a message set *mset*
- later p_i delivers m' in an other message set mset'
- ▶ Global SCD-delivery order: $\mapsto = \bigcup_{i=1}^{n} \mapsto_{i}$

 \blacktriangleright \mapsto is a partial order

- Let \leq be some total order extending \mapsto
 - ▶ processes scd-deliver sections of \leq

A containment property

let ms^x_i the x-th message set scd-delivered by p_i

$$\blacktriangleright \text{ let } MS_i^x = ms_i^1 \cup \cdots \cup ms_i^x$$

 $\blacktriangleright \forall i, j, x, y, (MS_i^x \subseteq MS_j^y) \lor (MS_j^y \subseteq MS_i^x)$

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Power - Sequentially consistent grow-only set

- 1 operation read():
- 2 return state;
- **3 operation** insert(v):
- scd-broadcast I(v); wait local delivery;
- 5 **event** scd-deliver $({I(v_1), ..., I(v_k)}):$ 6 | state \leftarrow state \cup { $v_1, ..., v_k$ }



Power – Atomic grow-only set

operation read():

- 2 scd-broadcast *Sync*; **wait** local delivery;
- 3 **return** *state*;
- 4 operation insert(v):
- 5 scd-broadcast I(v); wait local delivery;
- 6 event scd-deliver ({ $I(v_1), ..., I(v_k), Sync_1, ..., Sync_l$ }): 7 $\$ state \leftarrow state \cup { $v_1, ..., v_k$ }



Power – Sequentially consistent snapshot object

```
The MWMR snapshot object
abstract state: an array of registers
write(x, v): write v in register x
snapshot(): returns the whole array
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```
1 operation snapshot():
```

```
2 return Regs;
```

- **3 operation** write(x, v):
- 4 | let $\langle sn, j \rangle \leftarrow tsa[x]$; 5 | scd-broadcast Write $(x, v, \langle sn + 1, i \rangle)$; wait local delivery;
- 6 event scd-deliver (*mset*):
- 7

Power – Atomic snapshot object



- 1 operation snapshot():
- 2 scd-broadcast Sync; wait local delivery;
- 3 return Regs;
- 4 **operation** write(x, v):
- 5 scd-broadcast *Sync*; **wait** local delivery;
- 6 **let** $\langle sn, j \rangle \leftarrow tsa[x];$
- 7 scd-broadcast *Write*($x, v, \langle sn + 1, i \rangle$); wait local delivery;
- **8 event** scd-deliver (*mset*):
- 9 **foreach** $Write(x, v, ts) \in mset s.t. ts > tsa[x] do$

Power – Atomic snapshot object



- 1 operation snapshot():
- 2 scd-broadcast *Sync*; **wait** local delivery;
- 3 return Regs;
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- 5 scd-broadcast *Sync*; **wait** local delivery;
- 6 **let** $\langle sn, j \rangle \leftarrow tsa[x];$
- 7 scd-broadcast Write(x, v, (sn + 1, i)); wait local delivery;
- 8 event scd-deliver (*mset*):

9 **foreach**
$$Write(x, v, ts) \in mset s.t. ts > tsa[x] do$$

10 $\lfloor Regs[x] \leftarrow v; tsa[x] \leftarrow ts;$

Power – Remarks for software engineers

- 1 **operation** *snapshot*():
- scd-broadcast Sync; wait local delivery; 2
- return Regs; 3
- 4 operation write(x, v):
- 5 scd-broadcast *Sync*; **wait** local deliverv:
- 6 let $\langle sn, j \rangle \leftarrow tsa[x]$; 7 scd-broadcast $Write(x, v, \langle sn + 1, i \rangle)$; wait local delivery;
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- $Regs[x] \leftarrow v; tsa[x] \leftarrow ts;$ 10

Observations

- No quorum at this abstraction level!
- Each element plays its role:
 - structure, sequential consistency, overwriting, real-time
- Works for all objects with commutative/overwriting operations

Implementation - Shared memory

- 1 **operation** SCD-broadcast(m): $Reg[i] \leftarrow Reg[i] \cdot m$;
- 2 Regularly do:
- $3 \quad regs \leftarrow Reg.snapshot();$
- 4 $S \leftarrow \bigcup_{j=1}^{n} regs[j] \setminus delivered;$
- 5 **if** $S \neq \emptyset$ **then** SCD-deliver(S);

Consequences

- From sequential consistency to linearizability
- Equivalence SCD-broadcast/atomic register

SCD Previous slide Snapshot (projection) cadcast Above object Afek et Al.

Atomic register

- Consensus Number = 1
- Message-passing implementation : $t < \frac{n}{2}$

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 $\begin{array}{ccc} \text{SCD} & \begin{array}{c} \text{Previous slide} & \text{Snapshot} & (\text{projection}) \\ & \overbrace{\text{Above}} & \begin{array}{c} \text{object} & \\ & \text{Afek et Al.} \end{array} \end{array}$

- Consensus Number = 1
- Message-passing implementation : $t < \frac{n}{2}$

Atomic

register

Process p_{sd} SCD-broadcasts m

• each process p_f fifo-broadcasts forward(m, sd, sn_{sd} , f, sn_f)

Dependencies

- ▶ p_f views *m* before *m'* if
 - *p_f* sends *forward*(*m*, ·, ·, *f*, *sn_f*) and *forward*(*m'*, ·, ·, *f*, *sn'_f*)
 sn_f < *sn'_f*
- *p_i* knows that *p_f* has viewed *m* before *m'* if *p_i* received either
 forward(m, ·, ·, f, ·) but no *forward(m', ·, ·, f, ·)*
 - ▶ forward(m, \cdot, \cdot, f, sn_f) and forward($m', \cdot, \cdot, f, sn'_f$), $sn_f < sn'_f$
- *m* depends on m' (according to p_i) unless p_i knows that:
 - a majority of processes have viewed m before m'

- ▶ p_i can scd-deliver *mset* if for all $m \in mset$
 - *p_i* received *forward* messages from a majority
 - mset contains all non-delivered dependencies of m

Process *p*_{sd} SCD-broadcasts *m*

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m depends on *m*' (according to *p_i*) unless *p_i* knows that:

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Implementation - Complexity

SCD-broadcast

msgs: n^2 latency: 2 Δ (Δ : network delay)

Snapshot object

$\mathcal{O}(n)$	4Δ	$\mathcal{O}(n)$	2Δ
$\mathcal{O}(n^2 \log n)$	$\mathcal{O}(n \log n\Delta)$	$\mathcal{O}(n^2 \log n)$	$\mathcal{O}(n \log n\Delta)$
$\mathcal{O}(n^3)$	$\mathcal{O}(n\Delta)$		$\mathcal{O}(n\Delta)$
	2Δ	$\mathcal{O}(n^2)$	4Δ
	$0-4\Delta$	$\mathcal{O}(n^2)$	
		$\mathcal{O}(n^2)$	2Δ

[ABD] Attiya, Bar-Noy, Dolev. Sharing memory robustly in message-passing systems. JACM, 1995.
[AR] Attiya, Rachman. Atomic snapshots in O(nlog n) operations. SIAM Journal on Computing, 1998.
[DGFRR] Delporte-Gallet, Fauconnier, Rajsbaum, Raynal. Implementing snapshot objects on top of crash-prone asynchronous message-passing systems. ICA3PP, 2016.
[PPMJ] P., Petrolia, Mostefaoui, Jard. On Composition and Implementation of Sequential Consistency. DISC, 2016.

Implementation - Complexity

SCD-broadcast

msgs: n^2 latency: 2Δ (Δ : network delay)

Snapshot object

	Read / Snapshot		Write	
	# msgs	latency	# msgs	latency
ABD	$\mathcal{O}(n)$	4Δ	$\mathcal{O}(n)$	2Δ
ABD + AR	$\mathcal{O}(n^2 \log n)$	$\mathcal{O}(n \log n\Delta)$	$\mathcal{O}(n^2 \log n)$	$\mathcal{O}(n \log n\Delta)$
DGFRR	$\mathcal{O}(n^3)$	$\mathcal{O}(\mathit{n}\Delta)$	$\mathcal{O}(n)$	$\mathcal{O}(\mathit{n}\Delta)$
SCD-Atomic	$\mathcal{O}(n^2)$	2Δ	$\mathcal{O}(n^2)$	4Δ
PPMJ	0	$0-4\Delta$	$\mathcal{O}(n^2)$	0
SCD-Sequential	0	0	$\mathcal{O}(n^2)$	2Δ

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Perspectives – *k*-SCD broadcast

Can we limit the size of the message sets?

k-SCD broadcast

Definition: All message sets contain at most k messages Observation: 1-SCD broadcast \simeq Atomic broadcast

k-set agreement Extension of consensus

Termination: Each non-faulty process eventually decides a value

Validity: All decided values have been proposed

k-Agreement: At most k different values are decided

Theorem

k-SCD broadcast \simeq SCD broadcast + *k*-set agreement

[IMPR] Imbs, Mostéfaoui, P., Raynal. Which Broadcast Abstraction Captures k-Set Agreement? DISC 2017.

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Perspectives - MG-broadcast

Some operations do not commute

Monotonic Generic Broadcast

- Based on a conflict relation (like generic broadcast)
- Conflicting operations ordered inside message sets

Specific cases

- No conflicts: SCD-broadcast
- Only conflicts: Atomic broadcast

Consensus: only when necessary

[ERGPS] Enes, Rezende, Gotsman, P., Sutra. Fast State-Machine Replication via Monotonic Generic Broadcast. Report 2017.