Deep Learning et Réseaux de Neurones

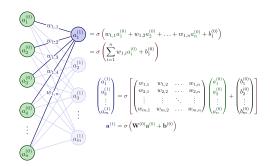
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Multi-Layers Architecture

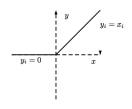
Neuron Unit

- A weight
- An activation function
- An output value



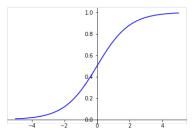
Rectified Linear Unit

- The most used function in Deep Learning.
- Apply a filter to the layer output by keeping only positive value.
- Relu_Function = max(0,x) Consequently the negative values are replaced by 0.
- The maximum value can be fixed by user, when output value are greater than the max they are replaced by it. This limits the output value range.



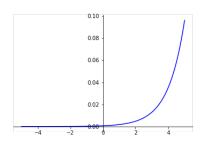
Sigmoid

- Used by the last network layer to apply the binary classification task.
- Equation : Sigmoid_function(x) = $1 / (1 + \exp(-x))$
- Can be view as the probability to belong to one class.
- In the case of a binary classification, the sum of all values is equal to



Softmax

- Also used to do a multi-class classification task.
- Can be used at the last layer level.
- Each output is between 0 and 1, the sum is equal to 1.
- Softmax_function(x) = $\exp(x)/\sup(\exp(x_i))$

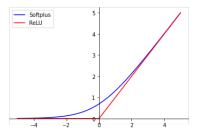


Softmax

- Results can be considered as probability to belong to a class.
- Each value is associated to a class.
- Sigmoid can't be used for the last layer into multi-class classification because in that case the sum is not equal to 0. Softmax has to be used in that case.

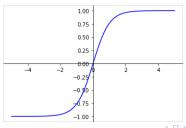
Softplus

- Soft approximation of ReLU function.
- If the input values are positive, the behavior is the same than ReLU.
- Difference with ReLU: no filter for negative value but values tend toward 0.
- Softplus_function (x) = log(exp(x) + 1)



tanh

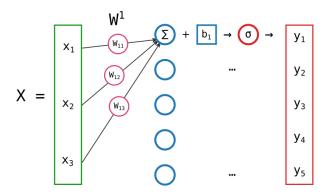
- Normalize the input values.
- Can replace Sigmoid function in binary classification task in the last layer.
- Range result values is -1 to 1, it can't be considered as a probability value.
- $tanh_function(x) = ((exp(x) exp(-x)) / (exp(x) + exp(-x))).$



Resume

- It exists a lot of another activation functions and more it is possible to design a new specific one for a purpose.
- Activation functions belong to the core of deep learning models.
- They apply non-linear transformations to data and allow to modify their spatial representation.
- Knowledge about their behavior is essential in deep learning design.
 Performances could be undermined by a wrong choice.

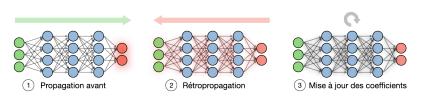
Forward Propagation



Learning Resume

3 steps

- Take the training data and apply forward propagation
- 2 Back propagate the loss to obtain the loss gradient of each coefficient.
- 3 Use the gradient to update the network coefficients.



Backpropagation

Goal

- Is a learning algorithm to improve the outputs.
- Correct the error by using the loss function.
- The loss function mesures the error level at each epoch in order to tell to the next one performances of the current weight values.
- To do it, gradient descent is computed and weights are adjusted to run the next epoch.
- Gradient descent with momentum, with a memory of previous gradient values, can be used to accelerate algorithm convergence.

Backward Propagation

Loss Functions

- Goal : minimize the error rates between prediction and groundtruth.
- Depending on data type, different functions have to be chosen.
- The result is after analyzed by gradient descent algorithm.
- Several optimizations are/can be done.

Break!

Tensor! What is it?

- Data structure essential in Deep learning.
- Can be viewed as multi-dimensional matrix.
- In PyTorch they are used for everything: input values, weights and bias, output results.
- All current matrix operations are available for tensors.
- Take care about the exponential explosion with the increase of dimensions.

Loss Functions

Which type?

- Regression function: to predict continuous results from independant variables.
- Classification function: to provide discret labels corresponding to a class.

Methods

- Regression: mean quadratic error (L2) mean absolute error (MAE).
 Idea: minimize the square error between predicted and target values.
 Allows to av
- Classification : Cross-entropy, log

Loss Functions

Performance evaluation

- Mean Square Error : Allows to penalize the outlier values.
- Cross entropie/log loss: computing from the difference between the two distributions values.

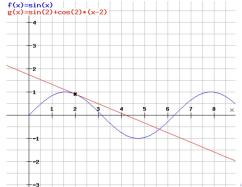
Equation : L(y,f(x)) = -[y * log(f(x)) + (1-y)* log(1-f(x))] where y is the binary value 0,1 of the label and f(x) the probability to belong to the positive class.

Penalize the wrong predictions - with a significative difference value from teh positive class.

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Methods

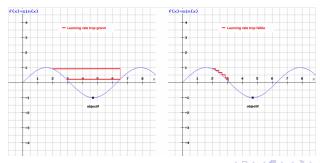
- Could be consider as the derivative function for tensors.
- Used to compute the evolution of f(x).
- Chosing the slope direction.



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Parameters

- Choose the learning rate : distance value to move on the slope.
 - if it is too small the time to compute will be enlarge and you can fall into a local minimum.
 - if it is too large the update can move you to an unreliable place on the slope



Parameters

- Choose the iteration number : how many times you move x on the slope.
 - if it is too small the descent will not have enough step to be realized and no optimisation.
 - if it is too large your computing time will be enlarge. In deep learning it is important to keep your time.

Backpropagation again!

- Applying the chain rule (https://en.wikipedia.org/wiki/Chain_rule):
- Gradient is computed for all weights and for all layers from the last to the first one.
- The goal is to compute the impact of each parameter and to modify it consequently.
- The loss is minimized through all iterations.

Network Performances

Methods

- Mean Absolute Error: mean sum of residual absolute values.
 To be used to mesure regression results. Several versions of this error are available. Can be used to check over-fitting.
- Accuracy : Acc = number of correct prediction/number of inputs. used for classification.
- Precision :
 Prec = number of True Positive/ (number of True Positive + number of False Positive)
- Recall :
 Rec = number of True Positive/ (number of True Positive + number of False Negative)
- F1-score : average between precision and recall
 F1 = (Prec * Rec) / (Prec + Rec)

Data Set

Choose the right sample

- Divide the data set into several parts :
 - Test set exclude 10 % of the whole set and keep it aside.
 - Training set most often 80% of the rest.
 - Validation set 20 % that remain.

Usage

- Test set has to be never seen at the training step.
- At each epoch training set is entirely seen. Inputs can be load in several steps depending the batch size.
- At the end of the epoch, the validation set is seen to measure the current network configuration performances.
- When the model is fixed, considered as trained, the test set is load to veryfy the capability to generalize the treatment.