The equivalence problem for Deterministic PushDown Automata

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0- MAIN RESULT

Decision problem:

INSTANCE: A, B, two deterministic pushdown automata;

QUESTION: L(A) = L(B)?

Raised in:

S. Ginsburg and S. Greibach, Deterministic Context-free languages, Information and Control, pages 620-648, 1966

0- MAIN RESULT

G. Sénizergues, L(A) = L(B)?, *Technical report*, LaBRI, Université Bordeaux I, report nr1161-97, 1997, Pages 1-71.

G. Sénizergues. The Equivalence Problem for Deterministic Pushdown Automata is Decidable. In *Proceedings ICALP 97*, pages 671–681. Springer, LNCS 1256, 1997.

G. Sénizergues, L(A) = L(B)? In *Proceedings INFINITY 97*, pages 1–26. Electronic Notes in Theoretical Computer Science 9.

0- MAIN RESULT

REFERENCE:

G. Sénizergues. L(A) = L(B)? decidability results from complete formal systems. *Theoretical Computer Science*, 251:1–166, 2001.

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1.1- Prefix matrices- Operations

Let us remark:

$$\langle \mathcal{P}(X^*), \cup, \cdot, \emptyset, \{\varepsilon\} \rangle \approx \langle \mathbb{B}\langle \langle X \rangle \rangle, +, \cdot, 0, 1 \rangle.$$

We rather use the second notation.

We call a series $S = \sum_{w \in X^*} S_w \cdot w$ prefix-free iff: for every $u,v \in X^*$,

$$(S_{uv}=1 \text{ and } S_u=1) \Rightarrow v=\varepsilon.$$

1.1- Prefix matrices- Operations

Definition 1 A row-vector $(A_1, \ldots, A_i, \ldots, A_m) \in (\mathbb{B}\langle\langle X \rangle\rangle)^n$ is said prefix-free iff

1-the supports of the A_i 's are disjoint 2- $\sum_{i=1}^{n} A_i$ is prefix-free.

Definition 2 A matrix $A \in (\mathbb{B}\langle\langle X \rangle\rangle)^{n \times m}$ is said prefix-free iff every row-vector $(A_{i,1}, \ldots, A_{i,j}, \ldots, A_{i,m})$ is prefix-free.

Example 3 Some prefix matrices:

$$\left(\begin{array}{cccc} ab & 0 & a^*c \\ ab & 0 & a^*c \end{array}\right), \quad \left(\begin{array}{cccc} ab & 0 & a^*c \\ 1 & 0 & 0 \\ abc & abd & a^*cd \end{array}\right), \quad \left(\begin{array}{c} a \\ ab^*c \\ abc+ac \end{array}\right)$$

1.1- PREFIX MATRICES- OPERATIONS

Product: defined as usual.

Let
$$A, B \in (\mathbb{B}\langle\langle X \rangle\rangle)^{1\times m}$$
 and $1 \leq j_0 \leq m$.

If
$$A = (a_1, ..., a_j, ..., a_m), B = (b_1, ..., b_j, ..., b_m)$$
 then

$$A\nabla_{j_0}B = (a_1 + a_{j_0} \cdot b_1, \dots, a_{j_0-1} + a_{j_0} \cdot b_{j_0-1}, 0, a_{j_0+1} + a_{j_0} \cdot b_{j_0+1}, \dots, a_m + a_{j_0} \cdot b_m)$$

$$\nabla_{j_0}^*(A) = (a_{j_0}^* \cdot a_1, \cdots, a_{j_0}^* \cdot a_{j_0-1}, 0, a_{j_0}^* \cdot a_{j_0+1}, \cdots, a_{j_0}^* \cdot a_m)$$

1.1- PREFIX MATRICES- OPERATIONS

We denote by $D\mathbb{B}_{n,m}\langle\langle X \rangle\rangle$ the set of prefix matrices (which will turn out to be a particular case of Deterministic matrices).

Lemma 4 Let
$$A \in \mathbb{DB}_{n,m}\langle\langle X \rangle\rangle, B \in \mathbb{DB}_{m,s}\langle\langle X \rangle\rangle$$
. Then $A \cdot B \in \mathbb{DB}_{n,s}\langle\langle X \rangle\rangle$

Lemma 5 Let $A, B \in \mathbb{DB}_{1,m}\langle\langle X \rangle\rangle$ and $1 \leq j_0 \leq m$. Then $1 - A\nabla_{j_0}B \in \mathbb{DB}_{1,m}\langle\langle X \rangle\rangle$ $2 - \nabla_{j_0}^*(A) \in \mathbb{DB}_{1,m}\langle\langle X \rangle\rangle$

1.2- PREFIX MATRICES- RIGHT-ACTION

Definition 6 Let $S = \sum_{w \in X^*} S_w \cdot w$ and $u \in X^*$. Then

$$S \bullet u = \sum_{w \in X^*} S_{u \cdot w} \cdot w,$$

(i.e. $S \bullet u$ is the *left-quotient* of S by u , or the *residual* of S by u).

This right-action is extended componentwise to matrices.

Lemma 7 Let $A \in \mathbb{DB}_{n,m}\langle\langle X \rangle\rangle$ and $u \in X^*$. Then $A \bullet u \in \mathbb{DB}_{n,m}\langle\langle X \rangle\rangle$

1.2- PREFIX MATRICES- RIGHT-ACTION

Lemma 8 Let $S \in D\mathbb{B}_{1,m}\langle\langle W \rangle\rangle$, $T \in \mathbb{B}_{m,s}\langle\langle W \rangle\rangle$ and $u \in W^*$. Exactly one of the following cases is true:

- (1) $\exists j, S_j \bullet u \not\in \{\emptyset, \epsilon\}$ in this case $(S \cdot T) \bullet u = (S \bullet u) \cdot T$.
- (2) $\exists j_0, \exists u', u'', u = u' \cdot u'', S_{j_0} \bullet u' = \epsilon;$ in this case $(S \cdot T) \bullet u = T_{j_0,*} \bullet u''.$
- (3) $\forall j, \forall u' \leq u, S_j \bullet u = \emptyset, S_j \bullet u' \neq \epsilon;$ in this case $(S \cdot T) \bullet u = \emptyset = (S \bullet u) \cdot T.$

1.3- PREFIX MATRICES- LINEAR IDENTITIES

Fundamental remark((Meitus 1989)):

Let $S_1, \ldots, S_j, \ldots, S_m \in D\mathbb{B}\langle\langle X \rangle\rangle$ and let $\vec{\alpha}, \vec{\beta} \in D\mathbb{B}_{1,m}\langle\langle X \rangle\rangle$ such that

$$(0)\sum_{j=1}^{m} \alpha_j \cdot S_j = \sum_{j=1}^{m} \beta_j \cdot S_j$$

Then one of cases (1),(2) must occur:

(1)
$$\vec{\alpha} = \vec{\beta}$$

(2)
$$\exists j_0 \in [1, m], \exists \vec{\gamma} \in \mathsf{D}\mathbb{B}_{1,m} \langle \langle X \rangle \rangle, \gamma_{j_0} = 0$$
, such that

$$S_{j_0} = \sum_{1 \le j \le m} \gamma_j \cdot S_j$$
.

1.3- Prefix matrices- Linear identities

Sketch of proof: Let $S = (S_j)_{1 \leq j \leq m} \in D\mathbb{B}_{m,1} \langle \langle X \rangle \rangle$. Suppose that $\vec{\alpha} \neq \vec{\beta}$. Let us consider

$$u = \min\{\vec{\alpha}\Delta\vec{\beta}\}.$$

Then there exists, $j_0 \in [1, m]$, such that

$$\vec{\alpha} \bullet u = \epsilon_{j_0}^m \Leftrightarrow \beta_{j_0} \bullet u \neq \epsilon_{j_0}^m.$$

Let us suppose, for example, that $\vec{\alpha} \bullet u = \epsilon_{j_0}^m$ while $\vec{\beta} \bullet u \neq \epsilon_{j_0}^m$ and let $\vec{\gamma} = \vec{\beta} \bullet u$. Let u act (by \bullet) on both sides of hypothesis (0):

$$(\vec{\alpha} \cdot S) \bullet u = (\vec{\beta} \cdot S) \bullet u. \tag{1}$$

Using lemma 8 we obtain:

$$(\vec{\alpha} \cdot S) \bullet u = S_{j_0}. \tag{2}$$

Let us examine now the righthand-side of equality (1). Let $u' \prec u$. By minimality of u, $\vec{\beta} \bullet u'$ is a unit iff $\vec{\alpha} \bullet u'$ is a unit. But if $\vec{\alpha} \bullet u'$ is a unit, then $\vec{\alpha} \bullet u = \emptyset^m$, which is false. Hence $\vec{\beta} \bullet u'$ is not a unit. By lemma 8

$$(\vec{\beta} \cdot S) \bullet u = (\vec{\beta} \bullet u) \cdot S. \tag{3}$$

Let us plug equalities (2) and (3) in equivalence (1) and let us define $\vec{\gamma} = \vec{\beta} \bullet u$. We obtain:

$$S_{j_0} = \vec{\gamma} \bullet S$$
, where $\vec{\gamma} \neq \epsilon_{j_0}^m$.

Using Arden's lemma we get:

$$S_{j_0} = \sum_{j
eq j_0} \gamma_{j_0}^* \gamma_j \cdot S_j$$
 i.e. $S_{j_0} = ec{\gamma'} ullet S$

where $\vec{\gamma'} = \nabla^*_{j_0}(\vec{\gamma})$, hence $\gamma'_{j_0} = 0$. \diamondsuit

1.4.1- PREFIX MATRICES- BASES

A subset $V \subseteq D\mathbb{B}\langle\langle X \rangle\rangle$ is said to be a prefix space iff it is closed under linear combinations (with prefix vector of coefficients).

A set $\mathcal{F} = \{S_1, \dots, S_m\}$ (where $m = \operatorname{Card} \mathcal{F}$) is called:

- a generating subset of V iff

$$V = \{ \sum_{j=1}^{m} \alpha_j \cdot S_j \mid \vec{\alpha} \in \mathsf{D}\mathbb{B}_{1,m} \langle \langle X \rangle \rangle \}.$$

- a linearly independent set if, for every $\vec{\alpha}, \vec{\beta} \in D\mathbb{B}_{1,m} \langle \langle X \rangle \rangle$,

$$\vec{\alpha} \cdot \vec{S} = \vec{\beta} \cdot \vec{S} \Leftrightarrow \vec{\alpha} = \vec{\beta}$$

- a base of V iff, it is both a generating set of V and it is linearly independent.

1.4.1- PREFIX MATRICES- BASES

Proposition 9 Every finitely generated prefix space has a base. Moreover this base is unique.

Question: For what kind of series (i.e. languages) is the base of $V(\mathcal{F})$ computable from the set \mathcal{F} ?

1.4.2- PREFIX MATRICES- MOST GENERAL UNIFIER

Let $\vec{\alpha}, \vec{\beta} \in D\mathbb{B}_{1,m}\langle\langle X \rangle\rangle$. We call unifier for the pair $(\vec{\alpha}, \vec{\beta})$ any matrix $U \in D\mathbb{B}_{m,n}\langle\langle X \rangle\rangle$ $(n \geq 1)$ such that:

$$\vec{\alpha} \cdot U = \vec{\beta} \cdot U.$$

It is said to be a Most General Unifier iff, every unifier has the form $U \cdot T$ for some matrix $T \in D\mathbb{B}_{n,s}$ (where $s \geq 1$).

1.4.2- PREFIX MATRICES- MOST GENERAL UNIFIER

Proposition 10 Every pair of prefix row-vectors $(\vec{\alpha}, \vec{\beta})$ has a MGU. This MGU is unique (except in the case where $0_{m,1}$ is a MGU).

Question: For what kind of series (i.e. languages) is the MGU computable from the pair of prefix row-vectors?

1.5- PREFIX MATRICES- EXAMPLE

A linear equation:

$$ab \cdot U_1 + 0 \cdot U_2 + aab \cdot U_3, 0 \cdot U_1 + abc \cdot U_2 + (aab + abd) \cdot U_3.$$

Computation of a MGU:

applying $\bullet ab$ on both sides:

$$U_1, \mathbf{c} \cdot U_2 + \mathbf{d} \cdot U_3.$$

substituting U_1 by the r.h.s:

$$abc \cdot U_2 + (aab + abd) \cdot U_3, abc \cdot U_2 + (abd + aab) \cdot U_3,$$

hence:

$$MGU((ab, 0, aab), (0, abc, (aab + abd)) = \left(egin{array}{c} c & d \ arepsilon & 0 \ 0 & arepsilon \end{array}
ight)$$

1.5- PREFIX MATRICES- EXAMPLE

A prefix column vector:

$$S = \begin{pmatrix} (ca^*b + d)a^*c \\ a^*ba^*c \\ a^*c \end{pmatrix}$$

This vector is a solution of:

$$ab \cdot S_1 + 0 \cdot S_2 + aab \cdot S_3, 0 \cdot S_1 + abc \cdot S_2 + (aab + abd) \cdot S_3.$$

Hence it is obtained by substitution from the MGU:

$$S_1 = cS_2 + dS_3$$

$$V(\{S_1, S_2, S_3\}) = V(\{S_2, S_3\})$$

A base of $V(\{S_1, S_2, S_3\})$ is $\{S_3\}$.

2.0- DETERMINISTIC MATRICES- DETERMINISTIC GRAMMARS

(Harrison-Havel, JCSS 1973):

Definition 11 Let $G = \langle X, V, P \rangle$ be some context-free grammar.

G is said strict deterministic iff there exists some equivalence relation \smile over $X \cup V$ such that

1- X is some class mod -

$$2\text{-}\ \forall v_1,v_1'\in V, \forall \alpha\in (X\cup V)^*, \forall w,w'\in V^*\text{,}$$
 if

$$v_1 \smile v_1', v_1 \rightarrow \alpha w_1, v_1' \rightarrow \alpha w_1'$$

then
$$(w_1=w_1'=\epsilon \ \text{and} \ v_1=v_1')$$
 or $\exists v_2,v_2'\in (X\cup V),w_2,w_2'\in (X\cup V)^*$,

$$v_2 \smile v_2', w_1 = v_2 w_2, w_1' = v_2' w_2'.$$

2.0- DETERMINISTIC MATRICES- DETERMINISTIC GRAMMARS

Theorem 12 (Harrison-Havel,73) A language $L \subseteq X^*$ is recognized (by empty stack) by some dpda **iff** it is generated by some strict-deterministic context-free grammar.

2.1- DETERMINISTIC MATRICES- OPERATIONS

Definition 13 A series $S \in \mathbb{B}\langle\langle\ V^*\ \rangle\rangle$ is said deterministic iff, for every words $\alpha, w_1, w_1' \in V^*$ such that $\alpha \cdot w_1, \alpha \cdot w_1' \in \operatorname{supp}(S)$ either $w_1 = w_1' = \epsilon$ or $(\exists v_2, v_2' \in V, w_2, w_2' \in V^*$, such that

$$v_2 \smile v_2', w_1 = v_2 w_2, w_1' = v_2' w_2'.$$

Intuition: a *deterministic* series is a generalized *configuration* of the initial pushdown automaton.

Definition 14 A row-vector $(S_1, \ldots, S_i, \ldots, S_m)$ is said deterministic iff

1-The supports of the S_i 's are disjoint $2-\sum_{j=1}^m S_i$ is deterministic.

Definition 15 A matrix of dimension (n,m), $(S_{i,j})_{1 \le i \le n, 1 \le j \le m}$ is said deterministic iff every one of its row-vectors is deterministic.

We denote by $D\mathbb{B}_{n,m}\langle\langle V \rangle\rangle$ the set of deterministic matrices.

2.1- DETERMINISTIC MATRICES- OPERATIONS

Lemma 16 Let $A \in \mathbb{DB}_{n,m}\langle\langle V \rangle\rangle$, $B \in \mathbb{DB}_{m,s}\langle\langle V \rangle\rangle$. Then $A \cdot B \in \mathbb{DB}_{n,s}\langle\langle V \rangle\rangle$

Lemma 17 Let $A,B\in \mathbb{DB}_{1,m}\langle\langle V \rangle\rangle$ and $1\leq j_0\leq m$. Then

$$1 - A \nabla_{j_0} B \in \mathsf{D}\mathbb{B}_{1,m} \langle \langle V \rangle \rangle$$

$$2$$
- $\nabla_{j_0}^*(A) \in \mathsf{D}\mathbb{B}_{1,m}\langle\langle V \rangle\rangle$

We define a σ -**right-action** \odot of the monoid X^* over the semi-ring $\mathbb{B}\langle\langle\ V^*\ \rangle\rangle$ by: for every $w\in V^*, u\in X^*$,

$$w \odot u = \sum_{\substack{w' \in V^* \\ w \longrightarrow_{lm}^* u \cdot w'}} w'$$

for every $S \in \mathbb{B}\langle\langle\ V^*\ \rangle\rangle, u \in X^*$,

$$\left(\sum_{w\in V^*} S_w \cdot w\right) \odot u = \sum_{w\in V^*} S_w \cdot (w \odot u).$$

This right-action is extended componentwise to matrices.

Lemma 18 Let $A \in \mathbb{DB}_{n,m}\langle\langle V \rangle\rangle$ and $u \in X^*$. Then $A \odot u \in \mathbb{DB}_{n,m}\langle\langle V \rangle\rangle$

Lemma 19 Let $S \in D\mathbb{B}_{1,m}\langle\langle W \rangle\rangle$, $T \in \mathbb{B}_{m,s}\langle\langle W \rangle\rangle$ and $u \in W^*$. Exactly one of the following cases is true:

- (1) $\exists j, S_j \odot u \not\in \{\emptyset, \epsilon\}$ in this case $(S \cdot T) \odot u = (S \odot u) \cdot T$.
- (2) $\exists j_0, \exists u', u'', u = u' \cdot u'', S_{j_0} \odot u' = \epsilon;$ in this case $(S \cdot T) \odot u = T_{j_0,*} \odot u''.$
- (3) $\forall j, \forall u' \leq u, S_j \odot u = \emptyset, S_j \odot u' \neq \epsilon;$ in this case $(S \cdot T) \odot u = \emptyset = (S \odot u) \cdot T.$

A map $\varphi: V \to \mathbb{B}\langle\langle X^* \rangle\rangle$ is defined by:

$$\varphi(v) = \sum_{v \odot u = \epsilon} u$$

This map is extended as a σ -additive **semi-ring homorphism** $\varphi: \mathbb{B}\langle\langle\ V\ \rangle\rangle \to \mathbb{B}\langle\langle\ X\ \rangle\rangle$ by

$$\varphi(\sum_{w \in V^*} S_w \cdot w) = \sum_{w \in V^*} S_w \cdot \varphi(w).$$

We set

$$S \equiv T \text{ iff } \varphi(S) = \varphi(T).$$

Lemma 20 For every

$$S \in \mathsf{D}\mathbb{B}_{n,m}\langle\langle\ V\ \rangle\rangle, T \in \mathsf{D}\mathbb{B}_{m,s}\langle\langle\ V\ \rangle\rangle, u \in X^*$$
 ,

$$1 - \varphi(S \cdot T) = \varphi(S) \cdot \varphi(T)$$

$$2 - \varphi(S \odot u) = \varphi(S) \bullet u$$

2.3- DETERMINISTIC MATRICES- LINEAR IDENTITIES

Fundamental remark:

Let $S_1, \ldots, S_j, \ldots, S_m \in D\mathbb{B}\langle\langle X \rangle\rangle$ and let $\vec{\alpha}, \vec{\beta} \in D\mathbb{B}_{1,m}\langle\langle X \rangle\rangle$ such that

(0)
$$\sum_{j=1}^{m} \alpha_j \cdot S_j \equiv \sum_{j=1}^{m} \beta_j \cdot S_j S$$

Then one of cases (1),(2) must occur:

(1)
$$\vec{\alpha} \equiv \vec{\beta}$$

(2)
$$\exists j_0 \in [1,m], \exists \vec{\gamma} \in \mathsf{D}\mathbb{B}_{1,m} \langle \langle X \rangle \rangle, \gamma_{j_0} = 0$$
, such that

$$S_{j_0} \equiv \sum_{1 \le j \le m} \gamma_j \cdot S_j$$
.

2.4.1- DETERMINISTIC MATRICES- BASES

A subset $V \subseteq D\mathbb{B}\langle\langle V \rangle\rangle$ is said to be a deterministic space iff it is closed under linear combinations (with deterministic vector of coefficients).

A set $\mathcal{F} = \{S_1, \dots, S_m\}$ (where $m = \operatorname{Card} \mathcal{F}$) is called:

- a generating subset of V iff

$$V = \{ \sum_{j=1}^{m} \alpha_j \cdot S_j \mid \vec{\alpha} \in D\mathbb{B}_{1,m} \langle \langle V \rangle \rangle \}.$$

- a linearly independent set if, for every $\vec{\alpha}, \vec{\beta} \in D\mathbb{B}_{1,m} \langle \langle V \rangle \rangle$,

$$\vec{\alpha} \cdot \vec{S} = \vec{\beta} \cdot \vec{S} \Leftrightarrow \vec{\alpha} \equiv \vec{\beta}$$

- a base of V iff, it is both a generating set of V and it is linearly independent.

2.4.1 - DETERMINISTIC MATRICES - BASES

Proposition 21 Every finitely generated deterministic space has a base. Moreover this base is unique (up to the equivalence \equiv).

It is unknown whether linear independence is a decidable property. It is unknown whether the base of $V(\mathcal{F})$ is computable from the set \mathcal{F} .

2.4.2- DETERMINISTIC MATRICES- MOST GENERAL UNIFIER

Let $\vec{\alpha}, \vec{\beta} \in D\mathbb{B}_{1,m}\langle\langle V \rangle\rangle$. We call unifier for the pair $(\vec{\alpha}, \vec{\beta})$ any matrix $U \in D\mathbb{B}_{m,n}\langle\langle V \rangle\rangle$ $(n \geq 1)$ such that:

$$\vec{\alpha} \cdot U \equiv \vec{\beta} \cdot U.$$

It is said to be a Most General Unifier iff, every unifier is equivalent (mod \equiv) to $U \cdot T$ for some matrix $T \in D\mathbb{B}_{n,s}$ (where $s \geq 1$).

2.4.2- DETERMINISTIC MATRICES- MOST GENERAL UNIFIER

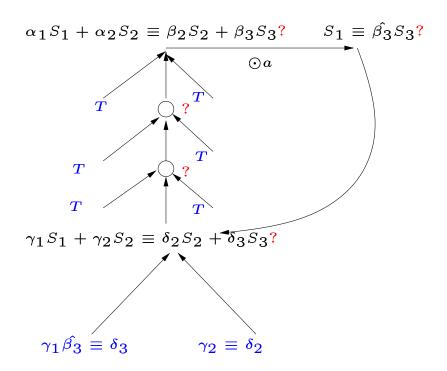
Proposition 22 Every pair of prefix row-vectors $(\vec{\alpha}, \vec{\beta})$ has a MGU. This MGU is unique (up to equivalence (mod \equiv), and with the exception of the case where $0_{m,1}$ is a MGU).

- The MGU is computable from the pair of prefix row-vectors.
- This will be a *corollary* of the main result ... hence *not* directly usable in its proof! We shall merely adapt the underlying idea.

3.1- DEDUCTION SYSTEMS- MOTIVATION

Let P be a set of equations such that, every equation is implied by the others. When can we conclude that they are all true?

3.1- DEDUCTION SYSTEMS- MOTIVATION



3.2- DEDUCTION SYSTEMS- GENERAL DEFINITIONS

General philosophy of (Harrison-Havel-Yehudai79), (Courcelle 83).

Let us call *deduction system* any triple $\mathcal{D} = \langle \mathcal{A}, H, \vdash - \rangle$ where

- \mathcal{A} is a denumerable set called the set of assertions
- $H: \mathcal{A} \to \mathbb{N} \cup \{\infty\}$ is the cost-function
- \models —, the *deduction relation* is a subset of $\mathcal{P}_f(\mathcal{A}) \times \mathcal{A}$ such that the following axioms are satisfied:

(A 1)
$$\forall (P,A) \in \vdash$$
—, (inf $\{H(p), p \in P\} < H(A)$) or $(H(A) = \infty)$.
(A 2) \vdash — is recursively enumerable.

We call *proof* in the system \mathcal{D} , any subset $P \subseteq \mathcal{A}$ fulfilling :

$$\forall p \in P, \exists Q \subseteq P, Q \vdash p.$$

3.2- DEDUCTION SYSTEMS- GENERAL DEFINITIONS

If P is a proof, then $\forall A \in P, H(A) = \infty$.

3.3- DEDUCTION SYSTEMS- STRATEGIES

Informal definition:

A strategy is a "method" allowing to enlarge every "partial proof" P into a partial proof Q with $P \subset Q$.

Notice: this method needs not be computable.

4.1- The system \mathcal{D}_0 - Assertions and cost function

Set of assertions:

$$\mathcal{A} = \mathbb{N} \times \mathsf{DRB}\langle\langle V \rangle\rangle \times \mathsf{DRB}\langle\langle V \rangle\rangle$$

The "cost-function":

$$H(n, S, S') = n + 2 \cdot \text{Div}(S, S').$$

Where the *divergence* between S and S', is defined by:

$$\operatorname{Div}(S, S') = \inf\{|u| | u \in \varphi(S) \triangle \varphi(S')\}.$$

(RO)

$$\{(p, S, T)\} \mid \vdash -(p+1, S, T)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle V \rangle\rangle$

(R1)

$$\{(p,S,T)\}\mid \vdash (p,T,S)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle V \rangle\rangle$,

(R2)

$$\{(p, S, S'), (p, S', S'')\} \mid \vdash (p, S, S'')$$

for $p \in \mathbb{N}, S, S', S'' \in DR\mathbb{B}\langle\langle V \rangle\rangle$,

(R3)

$$\emptyset \mid \vdash (0, S, S)$$

for $S \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle$,

(RO)

$$\{(p, S, T)\} \mid \vdash - (p+1, S, T)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DRB}\langle\langle V \rangle\rangle$,

(R1)

$$\{(p, S, T)\} \mid \vdash - (p, T, S)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle V \rangle\rangle$,

(R2)

$$\{(p, S, S'), (p, S', S'')\} \mid \vdash (p, S, S'')$$

for $p \in \mathbb{N}, S, S', S'' \in DR\mathbb{B}\langle\langle V \rangle\rangle$,

(R3)

$$\emptyset \mid \vdash (0, S, S)$$

for $S \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle$,

(R'3)

$$\emptyset \mid \vdash -(0, S, T)$$

for $S \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, T \in \{\emptyset, \epsilon\}, S \equiv T$,

(R4)

$$\{(p+1, S \odot x, T \odot x) \mid x \in X\} \mid \vdash (p, S, T)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, (S \not\equiv \epsilon \land T \not\equiv \epsilon)$,

(R5)

$$\{(p, S, S')\} \mid \vdash (p+2, S \odot x, S' \odot x)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle V \rangle\rangle, x \in X$,

(R6)

$$\{(p, S \cdot T' + S', T')\} \mid \vdash (p, S^* \cdot S', T')$$

(R'3)

$$\emptyset \mid \vdash -(0, S, T)$$

for $S \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, T \in \{\emptyset, \epsilon\}, S \equiv T$,

(R4)

$$\{(p+1, S \odot x, T \odot x) \mid x \in X\} \mid \vdash -(p, S, T)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, (S \not\equiv \epsilon \land T \not\equiv \epsilon)$,

(R5)

$$\{(p, S, S')\} \mid \vdash (p+2, S \odot x, S' \odot x)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DRB}(\langle V \rangle), x \in X$,

(R6)

$$\{(p, S \cdot T' + S', T')\} \mid \vdash (p, S^* \cdot S', T')$$

(R'3)

$$\emptyset \mid \vdash -(0, S, T)$$

for $S \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, T \in \{\emptyset, \epsilon\}, S \equiv T$,

(R4)

$$\{(p+1, S \odot x, T \odot x) \mid x \in X\} \mid \vdash -(p, S, T)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, (S \not\equiv \epsilon \land T \not\equiv \epsilon)$,

(R5)

$$\{(p, S, S')\} \mid \vdash (p+2, S \odot x, S' \odot x)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle V \rangle\rangle, x \in X$,

(R6)

$$\{(p, S \cdot T' + S', T')\} \mid \vdash (p, S^* \cdot S', T')$$

(R'3)

$$\emptyset \mid \vdash -(0, S, T)$$

for $S \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, T \in \{\emptyset, \epsilon\}, S \equiv T$,

(R4)

$$\{(p+1, S \odot x, T \odot x) \mid x \in X\} \mid \vdash (p, S, T)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle, (S \not\equiv \epsilon \land T \not\equiv \epsilon)$,

(R5)

$$\{(p, S, S')\} \mid \vdash (p+2, S \odot x, S' \odot x)$$

for $p \in \mathbb{N}, S, T \in \mathsf{DRB}(\langle V \rangle), x \in X$,

(R6)

$$\{(p, S \cdot T' + S', T')\} \mid \vdash (p, S^* \cdot S', T')$$

(R7)

$$\{(p,S,S'),(p,T,T')\}\mid \models -(p,S+T,S'+T')$$
 for $p\in\mathbb{N},(S,T),(S',T')\in\mathsf{DRB}_{1,2}\langle\langle\ V\ \rangle\rangle$,

(R8)

$$\{(p, S, S')\} \mid \vdash -(p, S \cdot T, S' \cdot T)$$

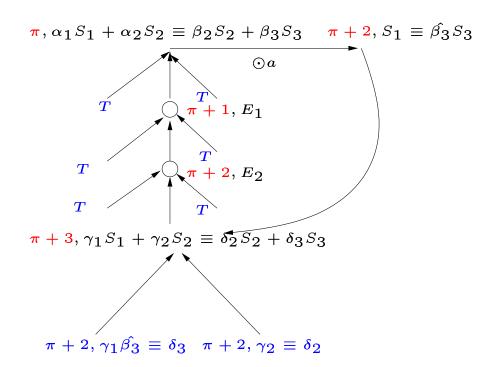
for $p \in \mathbb{N}, S, S', T \in DR\mathbb{B}\langle\langle V \rangle\rangle$,

(R9)

$$\{(p,T,T')\} \mid \vdash -(p,S\cdot T,S\cdot T')$$

for $p \in \mathbb{N}, S, T, T' \in \mathsf{DRB}\langle\langle V \rangle\rangle$,

4.3- The system \mathcal{D}_0 - Example



$$[q_{0}A\Omega\bar{q}] \equiv [q_{1}A\Omega\bar{q}] \quad (1)$$
 i.e.,up to some series equivalent to \emptyset
$$[q_{0}Aq_{1}][q_{1}\Omega\bar{q}] + [q_{0}Aq_{2}][q_{2}\Omega\bar{q}] \equiv [q_{1}Aq_{1}][q_{1}\Omega\bar{q}] + [q_{1}Aq_{2}][q_{2}\Omega\bar{q}]$$

$$t \qquad \qquad | a \\ [q_{0}TA\Omega\bar{q}] \equiv [q_{1}TA\Omega\bar{q}] \qquad [q_{1}D\bar{q}] \equiv [q_{1}B\Omega\bar{q}]$$

$$t \qquad | a \\ [q_{1}\Omega\bar{q}] \equiv [q_{1}\Omega\bar{q}] \quad [q_{1}D\bar{q}] \equiv [q_{2}\Omega\bar{q}][q_{1}A\Omega\bar{q}] \equiv [q_{1}A\Omega\bar{q}]$$

$$t \qquad | Teq \qquad | d \qquad Teq$$

$$[q_{0}TTA\Omega\bar{q}] \equiv [q_{1}TTA\Omega\bar{q}] \quad [q_{0}A\Omega\bar{q}] \equiv [q_{1}A\Omega\bar{q}]_{\epsilon} \equiv \epsilon \qquad (T_{cut}) \qquad (T_{\epsilon})$$

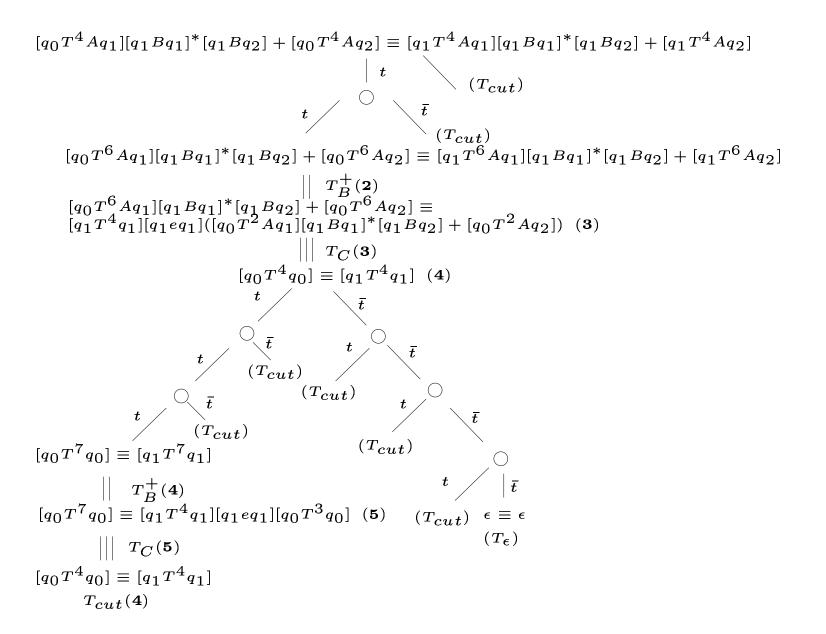
$$[q_{0}T^{3}A\Omega\bar{q}] \equiv [q_{1}T^{3}A\Omega\bar{q}] \qquad [q_{1}T^{3}Aq_{1}][q_{1}\Omega\bar{q}] + [q_{1}T^{3}Aq_{2}][q_{2}\Omega\bar{q}]$$
 i.e.
$$(T_{cut}) \qquad \text{up to some series equivalent to } \emptyset$$

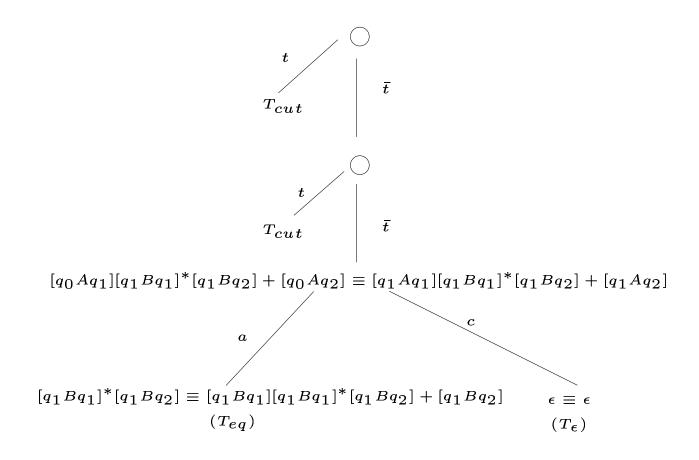
$$[q_{0}T^{3}Aq_{1}][q_{1}\Omega\bar{q}] + [q_{0}T^{3}Aq_{2}][q_{2}\Omega\bar{q}] \equiv [q_{1}T^{3}Aq_{1}][q_{1}D\bar{q}] + [q_{1}T^{3}Aq_{2}][q_{2}\Omega\bar{q}]$$

$$| | (T_{C}(1))$$

$$[q_{0}T^{3}Aq_{1}][q_{1}Bq_{1}]^{*}[q_{1}Bq_{2}] + [q_{0}T^{3}Aq_{2}] \equiv [q_{1}T^{3}Aq_{1}][q_{1}Bq_{1}]^{*}[q_{1}Bq_{2}] + [q_{1}T^{3}Aq_{2}] \quad (2)$$

$$\downarrow t \qquad \qquad \downarrow Left-Down part \quad (slide 55)$$





4.4- The system \mathcal{D}_0 - Strategies

We suppose $X = \{x_1, x_2\}$.

$$T_A$$

 A_1

 A_2

:

 A_{n-1}

 (π, S, T)

$$\angle$$

 $(\pi+1,S\odot x_1,T\odot x_1)$ $(\pi+1,S\odot x_2,T\odot x_2)$

$$T_B^+$$

$$\vdots$$

$$(\pi, S, \sum_{q \in Q} [\bar{p}zq] \cdot V_q$$

$$\vdots$$

$$\vdots$$

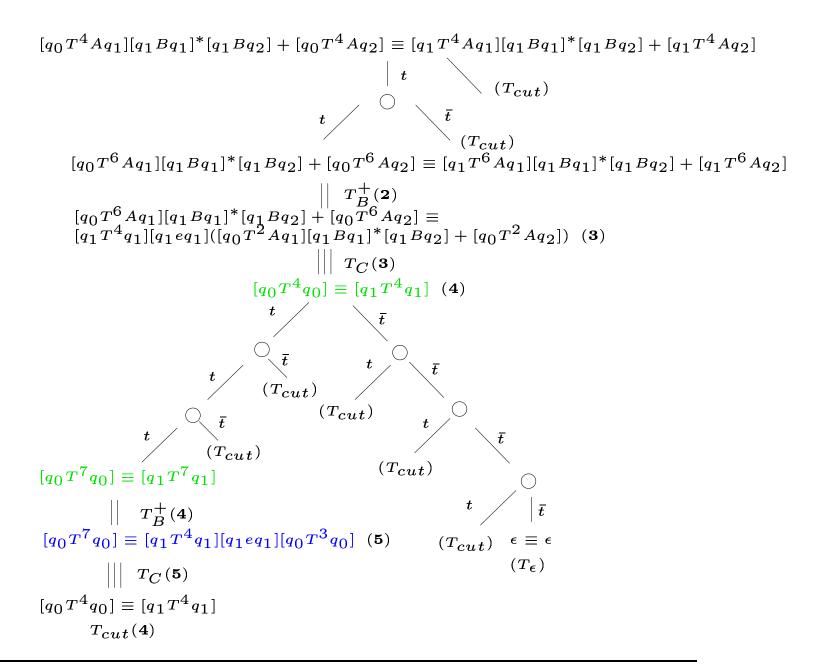
$$(\pi + k_1, S \odot u, \sum_{q \in Q} ([\bar{p}zq] \odot u) \cdot V_q$$

$$\downarrow$$

$$(\pi + k_1 - 1, S \odot u, \sum_{q \in Q'} ([\bar{p}zq] \odot u) \cdot (S \odot u_q)$$

where $Q' = \{q \in Q \mid [\bar{p}zq] \not\equiv \emptyset\}$ and $u_q = \min(\varphi([\bar{p}zq]))$

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 T_{C} : an example.

$$\pi, \alpha_{1}S_{1} + \alpha_{2}S_{2} + \alpha_{3}S_{3} \equiv \beta_{1}S_{1} + \beta_{2}S_{2} + \beta_{3}S_{3}
\vdots
\pi + 3, \gamma_{1}S_{1} + \gamma_{2}S_{2} + \gamma_{3}S_{3} \equiv \delta_{1}S_{1} + \delta_{2}S_{2} + \delta_{3}S_{3}
\downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow
\pi + 2, \gamma_{1}\hat{\beta}_{3} + \gamma_{3} \equiv \delta_{1}\hat{\beta}_{3} + \delta_{3} \quad \pi + 2, \gamma_{2} \equiv \delta_{2}$$

We know that first equation $\ \ -\pi + 2$, $S_1 \equiv \hat{\beta}_3 S_3$, hence {first equation, result of T_C } $\ \ --$ second equation.

4.4- The system \mathcal{D}_0 - Strategies

 T_C : general case.

 (π_1, U_1, V_1) (π_2, U_2, V_2) (π_D, U_D, V_D) $\mathcal{E}_1 \dots \mathcal{E}_j \dots \mathcal{E}_m$

5.1- DECIDABILITY- TERMINATING STRATEGY

The strategy S_{ABC} is a deterministic strategy, choosing for every branch to stop the construction of that branch or to add some new assertions (by means of

 T_A, T_B, T_C). Transformation T_C has highest prority.

idea 1: Successive applications of T_A, T_B on a branch make it smooth: from some point, many assertions have both sides on a given deterministic space

$$V(S_1,\ldots,S_n)$$

with n uniformly bounded (bound d_0 :exponential)

idea 2: on a smooth (hypothetically) infinite branch, T_C must be applicable, with some uniform bound on the size of the result (bound $\Sigma_0 + s_0$:not known to be p.r.)

5.2- DECIDABILITY- SYSTEM \mathcal{D}_0 IS COMPLETE

Theorem 23 The system \mathcal{D}_0 is complete.

Sketch of proof: From every true assertion (0, S, T), \mathcal{S}_{ABC} constructs a proof-tree. If the tree is infinite, then it has some infinite branch. T_C cannot apply i.o. on that branch (because its results are bounded). Hence an infinite suffix is smooth. But T_C is always applicable on such a path, hence \mathcal{S}_{ABC} should apply T_C : contradiction! Hence the tree (hence the proof) is finite. \diamondsuit

5.3- DECIDABILITY- TWO SEMI-DECISION ALGORITHMS

Theorem 24 The equivalence problem for deterministic pushdown automata is decidable.

Sketch of proof: Let $S,T\in \mathrm{DR}\mathbb{B}\langle\langle\ V\ \rangle\rangle$. 1- $S\equiv T$ is semi-decidable: just enumerate the finite \mathcal{D}_0 -proofs, until you find a proof P containing (0,S,T). 2- $S\not\equiv T$ is semi-decidable: just enumerate the words $w\in X^*$, until you find a witness w such that $S\odot w=\varepsilon\Leftrightarrow T\odot w\neq\varepsilon$. \diamondsuit

6.1- REFINEMENTS-EXTENSIONS-COMPLEXITY

Theorem 25 (Stirling, ICALP'02)The equivalence problem for dpda's is primitive recursive.

6.2- REFINEMENTS-EXTENSIONS-BISIMULATION

Theorem 26 (Sénizergues, FOCS'98)The bisimulation problem for non-deterministic pushdown automata, with deterministic, decreasing ϵ -moves, is decidable.

To appear in (SIAM, 2005).

6.3- REFINEMENTS-EXTENSIONS-TRANSDUCERS

Theorem 27 (Sénizergues, ICALP'99)The equivalence problem for deterministic pushdown transducers, from X^* , into a free group, is decidable.

Theorem 28 (Sénizergues, ICWL'00, Kyoto)The equivalence problem for deterministic pushdown transducers, from X^* , into $(\mathbb{Q}, +, \times)$, over two rational series S, T, which are supposed

1- \(\sigma\)-deterministic

2- but might be non-V-deterministic rational is decidable.

Work in progress.

7- PERSPECTIVES

Open question 0:

Is linear independence a decidable property?.

Open problem 1:

Develop the theory of prefix (resp. deterministic) matrices. (Monoid of square matrices, deterministic spaces)

Open problem 2:

Find a non-trivial lower-bound for the complexity of the equivalence problem for dpda.

Open problem 3:

Find a better upper-bound for the complexity of the equivalence problem for dpda.

7- PERSPECTIVES

Open problem 4:

Show that the following problem is decidable:

INSTANCE: a deterministic pushdown transducer $X^* \to \mathbb{H}$ (the

quaternions over Q), and two rational —-deterministic,

non-V-deterministic series $S, T \in \mathbb{RH}(\langle V \rangle)$.

QUESTION: Are the series S, T bisimilar?

7- PERSPECTIVES

i.e. does there exist a binary relation $\mathcal R$ over $\mathrm{RH}\langle\langle\ V\ \rangle\rangle$ such that:

1- $\forall (U,U') \in \mathcal{R}, \forall x \in X$, and for every choice of $U_1 \in U \odot x$, there exists a choice $U_1' \in U' \odot x$ such that $(U_1,U_1') \in \mathcal{R}$ 1'- $\forall (U,U') \in \mathcal{R}, \forall x \in X$, and for every choice of $U_1' \in U' \odot x$, there exists a choice $U_1 \in U \odot x$ such that $(U_1,U_1') \in \mathcal{R}$ 2- $\forall (U,U') \in \mathcal{R}, (U \in \mathbb{H} \Rightarrow U = U')$. 2'- $\forall (U,U') \in \mathcal{R}, (U' \in \mathbb{H} \Rightarrow U = U')$.