Consistency in Distributed Systems

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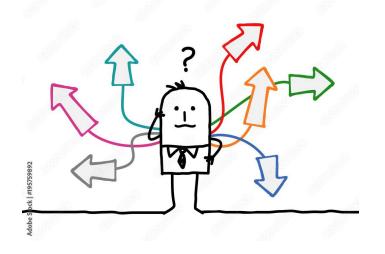
- Distributed shared data structures
- Safety properties and progress conditions
- Strong consistency (linearizability and sequential consistency)
- Weak consistency
- Progress conditions
- Conclusion

Distributed Computation

• Processes and concurrency

• Processes may interact directly through share data structures if there is a shared memory

• Or through messages exchanged by the different processes



Distributed shared data structures

- The basic operations are read/write on registers and possibly special instructions (C&S, T&S, ...)
- or, send/receive of messages through a communication network
- However shared data structures used by distributed applications may be more sophisticated: stacks, queues, sets, logs, graphs, etc.
- These data structures are not offered natively by processors
- Each operation on a shared data structure corresponds to a code (a function) that can be complex

Distributed shared data structures

• The push operation in Trieber/IBM's Stack (from D. Hendler)

```
Push(int v, Stack S)
  n := new NODE :create node for new stack item
1.
2. n.val := v :write item value
3. do forever ;repeat until success
    node top := S.top
4.
5.
    n.next := top ;next points to current top (LIFO order)
     if compare&swap(S, top, n) ; try to add new item
6.
                  : return if succeeded
7.
       return
   end do
8.
```

Distributed shared data structures

• The enqueue operation in Mickael & Scott's Queue (from D. Hendler)

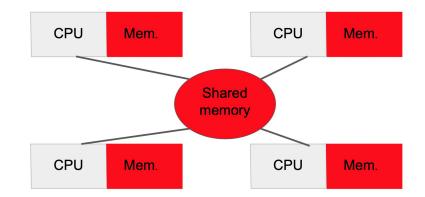
```
public boolean eng(T value) {
  Node node=new Node(value);
 while (true) {
    Node last = tail.get();
    Node next = last.next.get();
    if (last == tail.get()) {
       if (next == null) {
           if (last.next.compareAndSet(null,node) {
               tail.compareAndSet(last,node);
               return:
        } else {
           tail.compareAndSet(last,next);
```

Distributed Shared Data Structures

The ABD simulation (Attiya, Bar-Noy and Dolev 1995)

• It has been proved in 1995 that a shared memory (shared registers) can be emulated over a distributed system provided that there is a majority of processes that do not crash

However special instructions cannot be implemented on a message-passing system prone to process crashes



Consistency and Progress Conditions

- A data structure is defined by two properties:
 - A safety property
 - A progress condition
- Safety: It questions the meaningfulness of the results returned by operations on shared objects
- Progress: will there be a returned value and when?

Consistency and Progress Conditions

Safety properties

Ideally: The best consistency for an implemented shared object is the one that makes it indistinguishable from a physical object accessed concurrently

• One simple way to guarantee this property is to use locks: atomicity

O Locks do not tolerate process crashes

52% of bugs in Java concern the misuse of "synchronized"
 false conflicts

• Otherwise

complex implementation of data structures

memory consuming



Consistency and Progress Conditions

Progress conditions

Ideally: Each operation terminates whatever is the behavior of the other processes (contention, order, etc.)

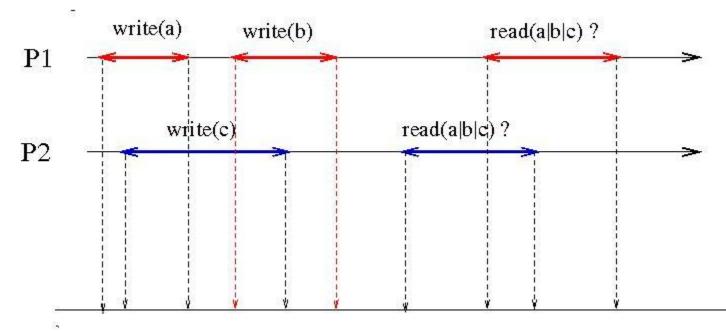
• If one uses locks there are three progress conditions • deadlock-free (global progress)

- o deadlock free (global progress)
 o starvation-free (local progress)
 o ffe
- fifo
- Otherwise
 - \circ wait-free (local progress)
 - lock-free (global progress)
 - obstruction-free (conditional progress no contention)

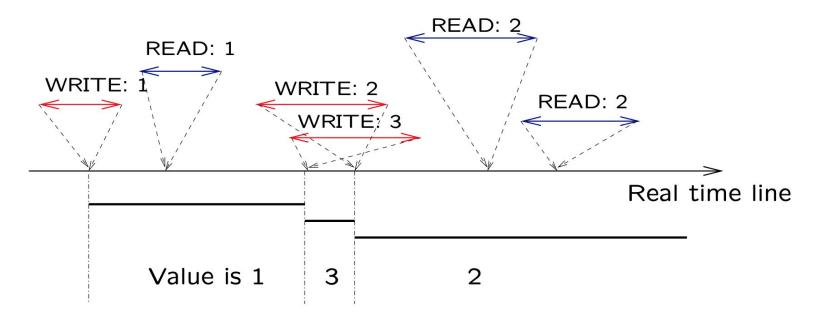


- Linearizability and sequential consistency are usually called strong consistency
- A process cannot distinguish a strongly consistent implementation of a data structure with a physical data structure accesses concurrently
 - Wait-free linearizable shared data structures are desirable but sometimes complex or inefficient
 - \odot Lock-free implementations may enjoy enough strong progress and acceptable complexity

• Linearizability (from M. Raynal)

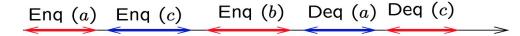


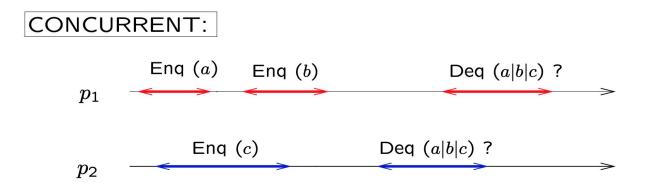
• Linearizability: a possible linearization

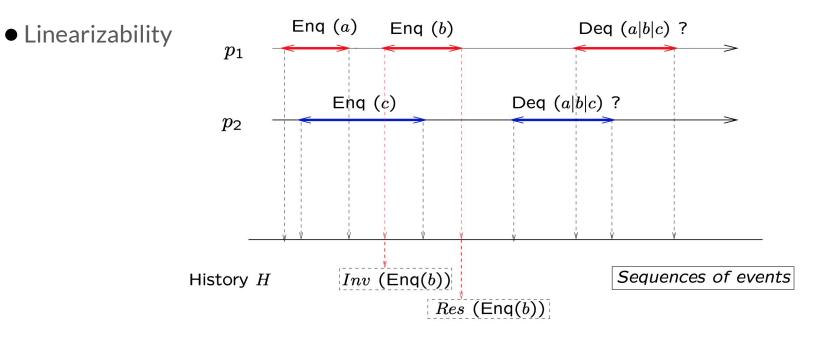


• Linearizability: a shared queue

SEQUENTIAL:

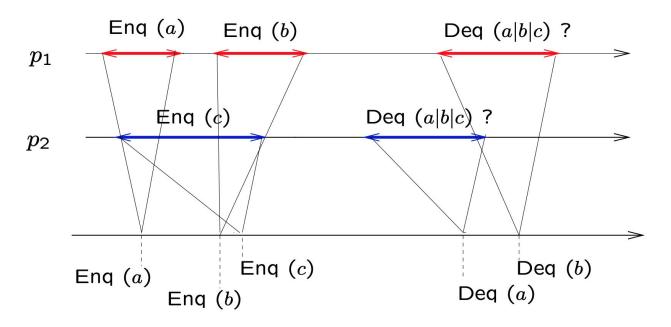




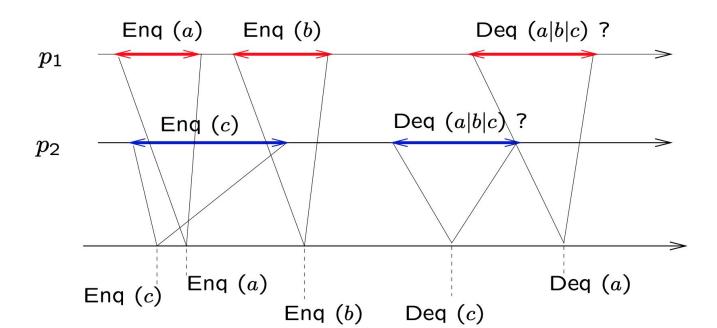


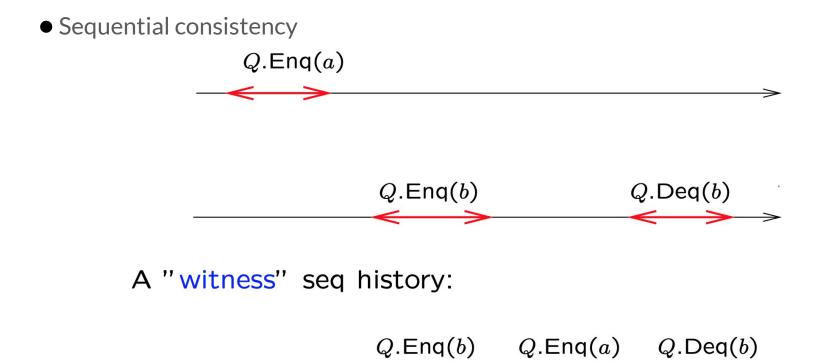
A history defines a partial order on the operations

• Linearizability

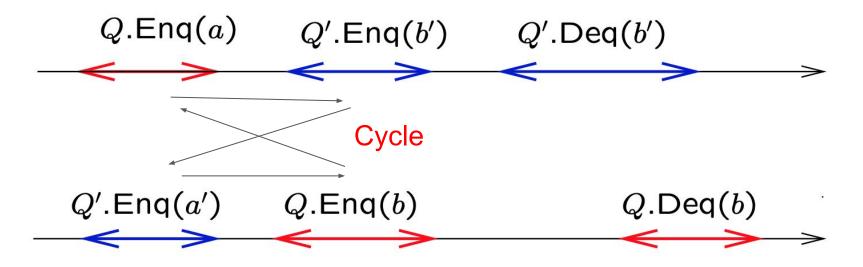


• Linearizability





• Sequential consistency: unfortunately, it does not compose!



- Linearizability and sequential consistency cannot be distinguished in an asynchronous system
- Sequential consistency is "cheaper" than linearizability
- However, linearizability is a local property: if all objects are linearizable, then the whole computation is linearizable!
- A distribution computation is a partial order of events.
- A good consistency criterion consists in totally ordering all events
 - linearizability: total order on all events + causality + real-time order
 - sequential consistency: total order on all events + causality

- Strong consistency is usually costly in time and space
- In message-passing systems strong consistency is usually not possible and when it is possible, operation has to last the latency of the communication network: CAP Theorem (Consistency - Availability - Partition) Gilbert&Lynch 2002
- Attiya & Welch proved in 1994 that, when possible, strong consistency needs an operation duration proportional with network latency
- This is practically impossible for many applications such as instant messaging, collaborative editors, etc.
- In those situations, one can use weak consistency conditions:
 - O Cache coherence
 - Causal consistency
 - Eventual consistency
 - PRAM consistency
 - Serializability ...

Weak consistency conditions let each process built its own total order

- Strong eventual consistency: same total order on all update operations
- Serializability (transactions in databases): not all operations terminate
- Causal consistency: all local linearization respect causal order
- PRAM consistency: local and fifo order

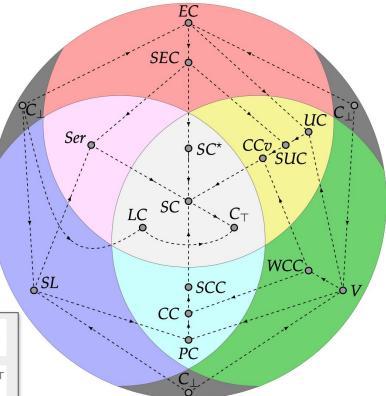
There is no total order on the strength of the different consistency conditions => which the strongest weak consistency condition ?

The world of consistency conditions (from M. Perrin PhD thesis)

There are 3 basic families of consistency conditions

A consistency condition that merges all of the three families falls into strong consistency

SC	PC	SEC	SUC	CCV	WCC	SCC	LC
Cohérence	Cohérence	Convergence	Cohérence	Convergence	Cohérence	Cohérence	Cohérence
séquentielle	pipeline	forte	d'écritures forte	causale	causale faible	causale forte	locale
SC* Cohérence de cache	SL Localité d'état	EC Convergence	UC Cohérence d'écritures	Ser Sérialisabilité	V Validité	CC Cohérence causale	$C_{\perp} C_{\top}$ Critères limites



Weak consistency for which usage

- Serialisability: substitute for strong consistency
 - maximal security
 - O simple to implement
 - $\,\circ\,$ failures are handled by the user
- Causal/PRAM consistency: distributed algorithms
 - predictable
 - O not costly
 - no convergence
- Update consistency/strong eventual consistency: collaborative applications
 - close to self-stabilization
 - quite costly
 - inconsistencies visible to the user

Small experience with instant messaging: Snapshat, Messenger, Whatsapp, Skype, Hangouts, etc.

- Hangouts: serializability • message sending can be aborted
- Whatsapp: PRAM consistency

○ local consistency (perhaps the least consistent instant messaging)

- Skype: strong eventual consistency
 - messages can be reordered afterwards (all users eventually see all messages in the same order)

Progress Conditions

- If one considers message-passing systems, when strong consistency is not possible, applications consider weak consistency as seen above.
 • Amazon's Dynamo highly available key-value store
- When necessary, whatever is the cost, strong consistency is provided
 Apache's Zookeeper for maintaining configuration information
 Google's Chubbby system
- In multithreaded computing, strong consistency is not sacrificed, but instead the progress condition is weakened: lock-free instead of wait-free

Progress Conditions

• The enqueue op. in Mickael & Scott's lock-free Queue (from D. Hendler)

```
public boolean eng(T value) {
  Node node=new Node(value);
 while (true) {
    Node last = tail.get();
    Node next = last.next.get();
    if (last == tail.get()) {
       if (next == null) {
           if (last.next.compareAndSet(null,node) {
               tail.compareAndSet(last,node);
               return;
        } else {
           tail.compareAndSet(last,next);
```

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Conclusion

- Lock-free implementation are less complex than wait-free ones but they offer weaker guarantees on progress
- In real settings, lock-free data structures statistically guarantee termination for all operations
- Mickael & Scott's lock-free linearizable queue is included in the Standard Java Concurrency Package
- There are many ongoing research to find the best special instructions and the most efficient distributed implementations of usual data structures