

# Spanner problems in temporal graphs

Arnaud Casteigts

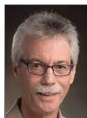
LaBRI, Université de Bordeaux

November 9, 2021

Based on joint works with:



Jason Schoeters



Joseph Peters



Michael Raskin



Malte Renken



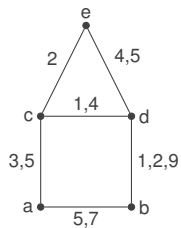
Viktor Zamaraev

# Temporal graphs

(a.k.a. time-varying, time-dependent, evolving, dynamic,...)

$\mathcal{G} = (V, E, \lambda)$ , where  $\lambda : E \rightarrow 2^{\mathbb{N}}$  assigns *presence times* to edges (here, discrete)

Example:

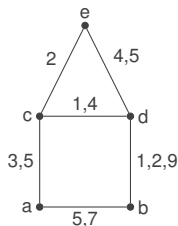


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## Temporal paths

▶ Ex:  $\langle (a, c, 3), (c, d, 4), (d, e, 4) \rangle$

(non-decreasing)

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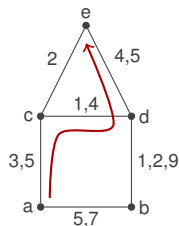
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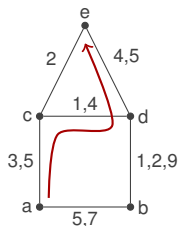
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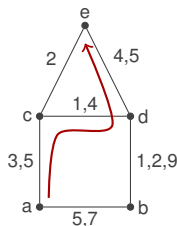
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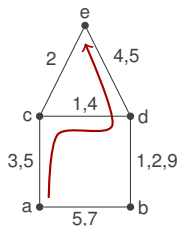
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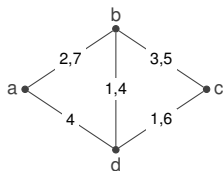
Remark: reachability is **non-transitive** in general!

## Temporal spanners

**Input:** a graph  $\mathcal{G}$  that is temporally connected ( $\mathcal{G} \in TC$ )

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**Cost measure:** size of the spanner (in number of time labels)



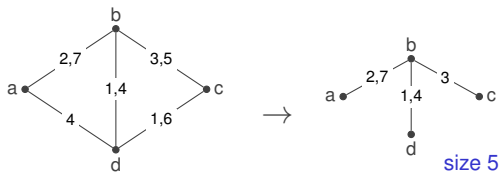


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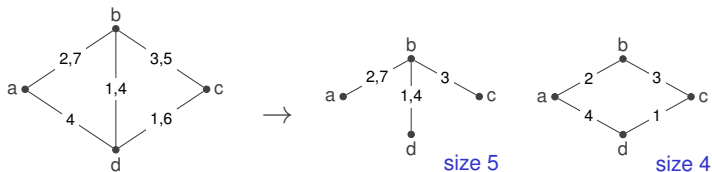


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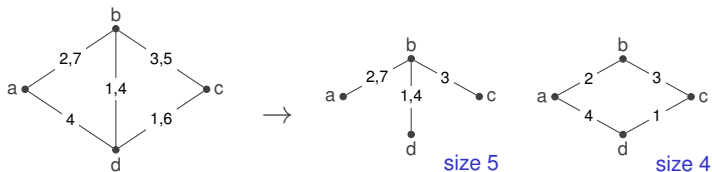


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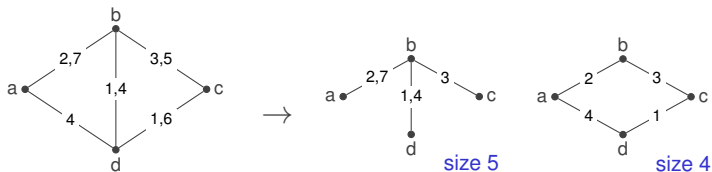
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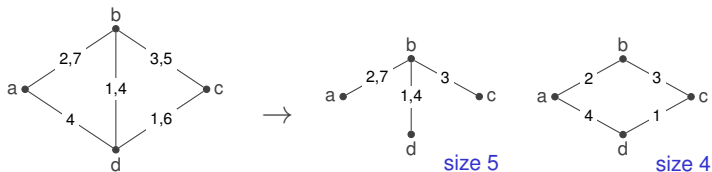
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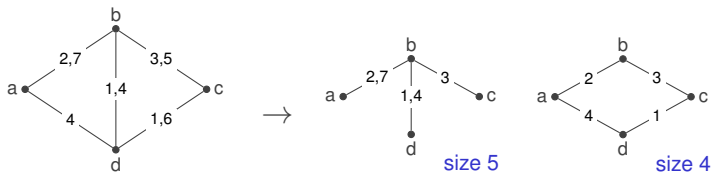
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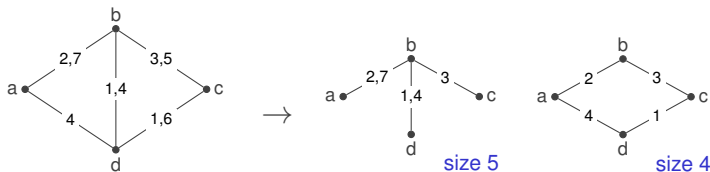
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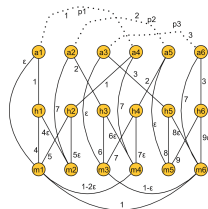
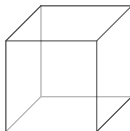
How about complexity?

- ▶ Computing minimum-size spanner is APX-hard (Akrida et al., 2017)

# What about the positive side?

Recall the bad news:

- ▶  $\Omega(n \log n)$  - easy
- ▶  $\Omega(n^2)$  - rather unexpected

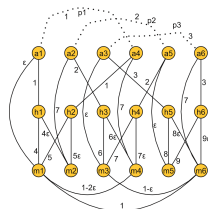
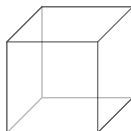




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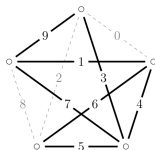
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## Good news 1: (C., Peters, Schoeters, ICALP 2019):

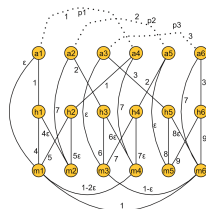
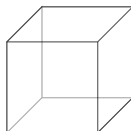
- ▶ Spanners of size  $O(n \log n)$  always exist in **complete** temporal graphs



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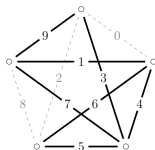
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## Good news 2: (C., Raskin, Renken, Zamaraev, FOCS 2021):

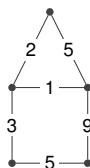
- ▶ Nearly optimal spanners (of size  $2n + o(n)$ ) almost surely exist in **random** temporal graphs, as soon as the graph is temporally connected



## Before we start... an easier model

### Simple Temporal Graphs (STGs):

1. A single presence time per edge ( $\lambda : E \rightarrow \mathbb{N}$ )
2. Adjacent edges have different times ( $\lambda$  is locally injective)

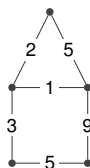




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### Generality for spanners:

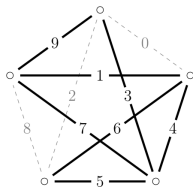
- ▶ Most negative results still apply
- ▶ Positive results extend to general case
- ▶ No distinction between **strict** and **non-strict** temporal paths

### Further motivations:

- ▶ Distributed models by pairwise interactions, e.g. **population protocols** or **gossip models** (without repetition)
- ▶ Topics in **edge-ordered graphs**

## Good news 1:

Temporal cliques admit sparse spanners



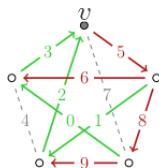
## Two promising techniques...

### Pivotability

Node  $v$  and time  $t$  such that:

- ▶ all nodes can reach  $v$  before  $t$
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Then **in-tree**  $\cup$  **out-tree** is a spanner of size  $2n - 2$





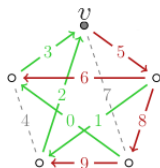
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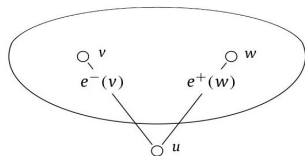


### Dismountability

Three nodes  $u, v, w$  such that:

- ▶  $uv = \text{min-edge}(v)$
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Then  $\text{spanner}(\mathcal{G}) := \text{spanner}(\mathcal{G}[V \setminus u]) + uv + uw$



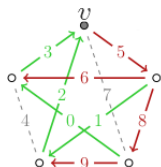
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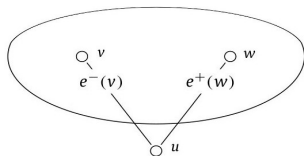


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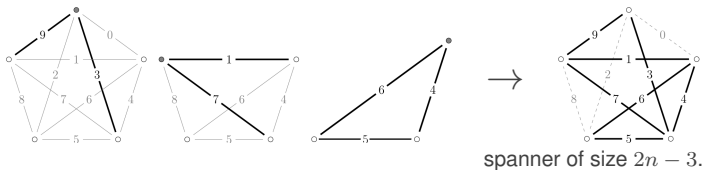
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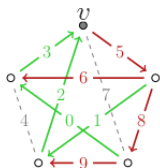
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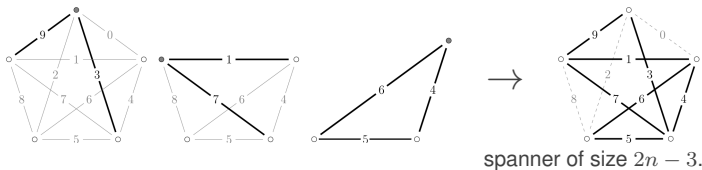
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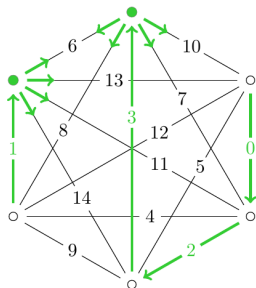
Both techniques fail in some cliques!

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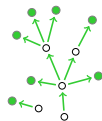
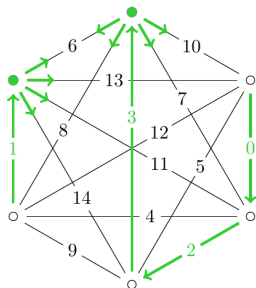


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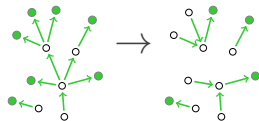
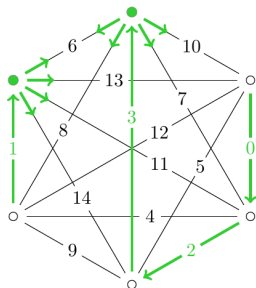
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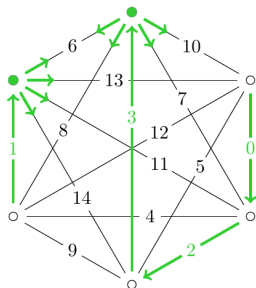
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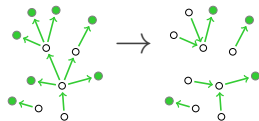


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**Theorem:**  $\exists$  spanners of size  $\frac{3}{4} \binom{n}{2} + O(n)$

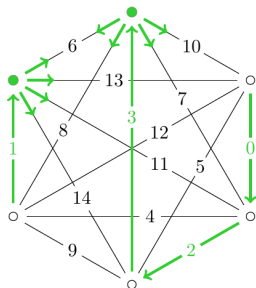




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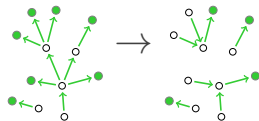


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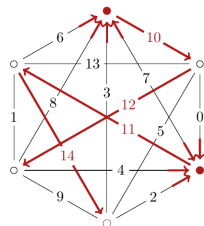
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Note: also works for receptions (“backward fireworks”):

$\rightarrow$  Spanner = max edges + all edges of **collectors**

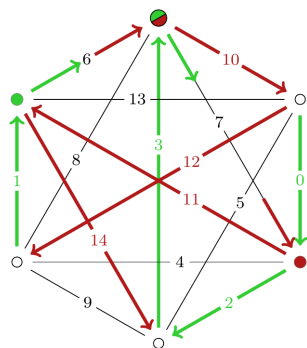


# Combining both directions

## Principle

- ▶ Every vertex can reach at least one emitter  $u$  through  $u$ 's min edge
- ▶ Every vertex can be reached by a collector  $v$  through  $v$ 's max edge
- ▶ Every emitter can reach all collectors through direct edges

→ Spanner = min edges + max edges  
+ edges between **emitters** and **collectors**



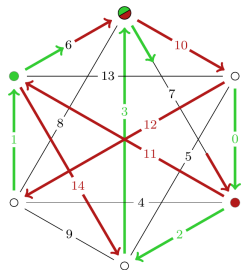
## Theorem:

At most  $n/2$  **emitters** and  $n/2$  **collectors**  $\Rightarrow$   $\exists$  Spanners of size  $\binom{n}{2}/2 + O(n)$   
 $\approx$  half of the edges

# Recurse or sparsify?

Two options:

- ▶ Case 1: **emitters**  $\cup$  **collectors**  $\neq V$
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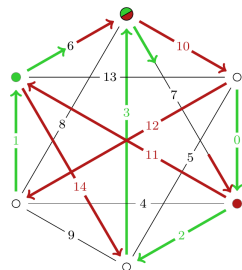
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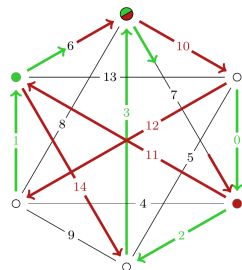
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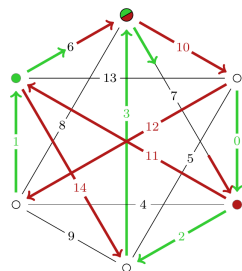
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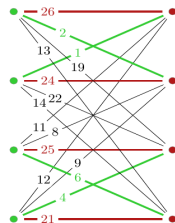
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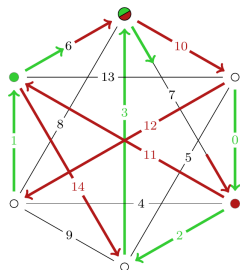
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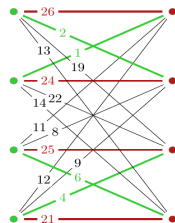


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A lot of structure to work with:

- ▶ Complete bipartite graph  $\mathcal{H}$  between emitters and collectors
- ▶ Min edges and max edges form two perfect matchings
- ▶ W.l.o.g. min edges (max edges) are *reciprocal* in  $\mathcal{H}$







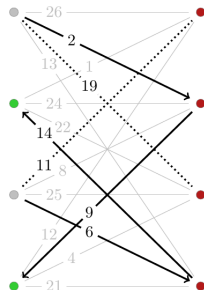
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New objective:

→ Sparsify  $\mathcal{H}$  while preserving journeys from each **emitter** to all **collectors**

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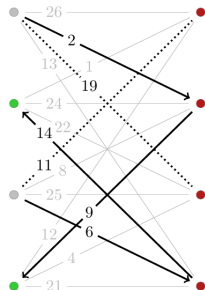
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In each step  $i$ :

- ▶ Half of the **emitters** partially delegate to other half
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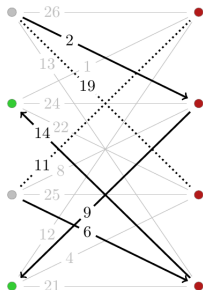
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Conclusion (entire algorithm):

→  $\exists$  spanner of size  $O(n) + O(n \log n) = O(n \log n)$ . □



Good news 2:

Spanners of size  $2n + o(n)$  almost surely exist  
in random temporal graphs

# Random Simple Temporal Graphs (RSTGs)

Temporal analog of Erdős-Reyni graphs, same parameters  $n$  and  $p$

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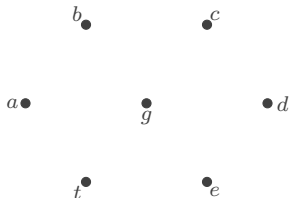
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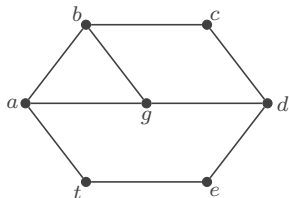
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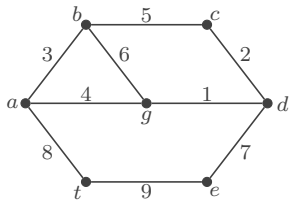
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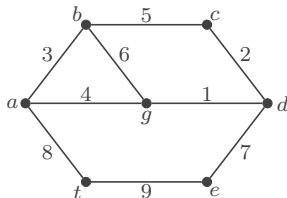
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Another point of view:

1. Take a complete graph  $K_n$
2. Assign random real times in  $[0, 1]$  to every edge
3. Restrict your attention to  $\mathcal{G}_{[0,p]}$

→ **Better for analysis.**

# Timeline of temporal reachability in $\mathcal{G}_{n,p}$

For sufficiently large  $n$ , what happens when  $p$  increases?



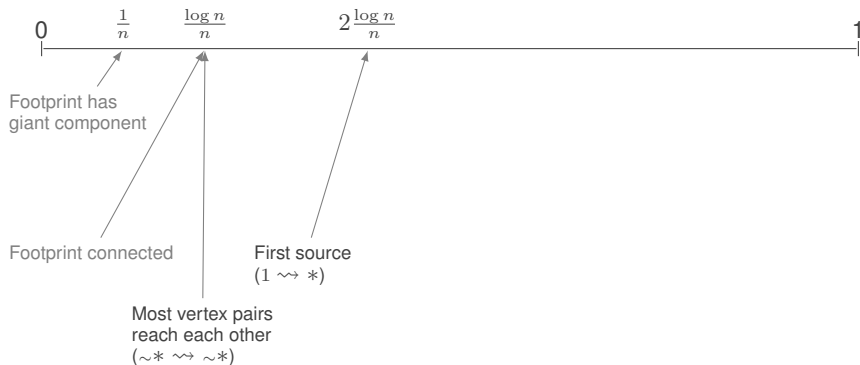
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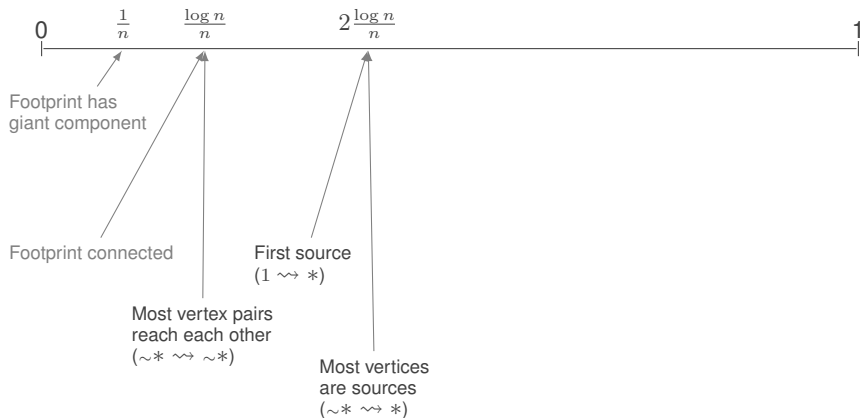
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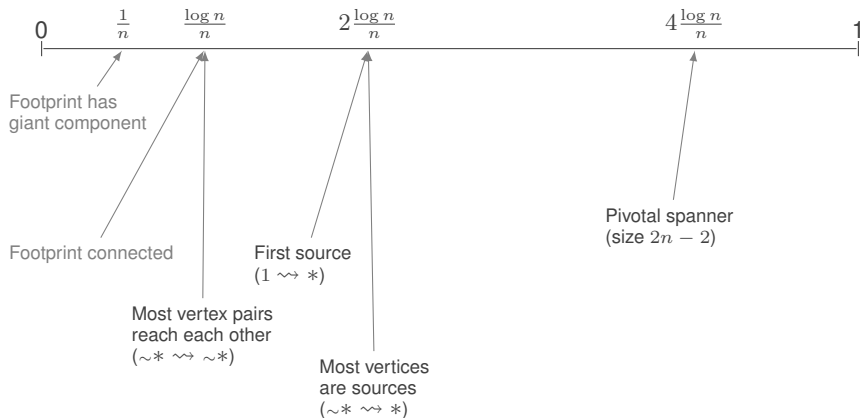
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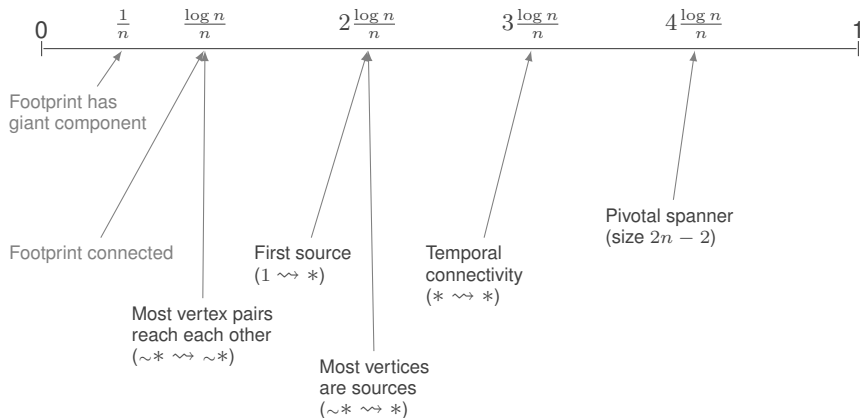
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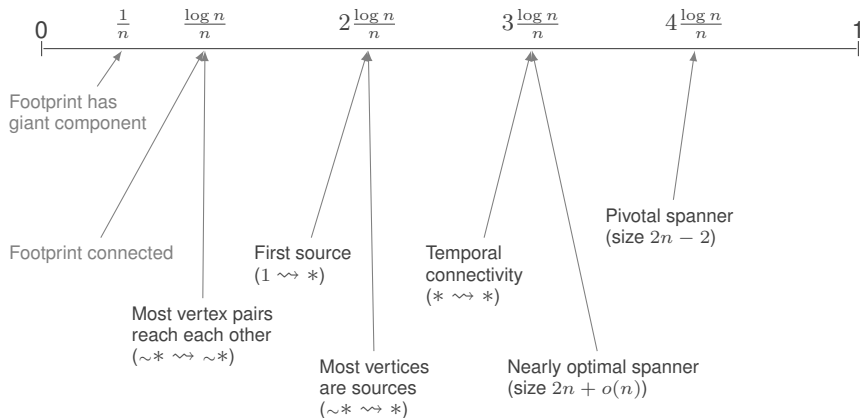
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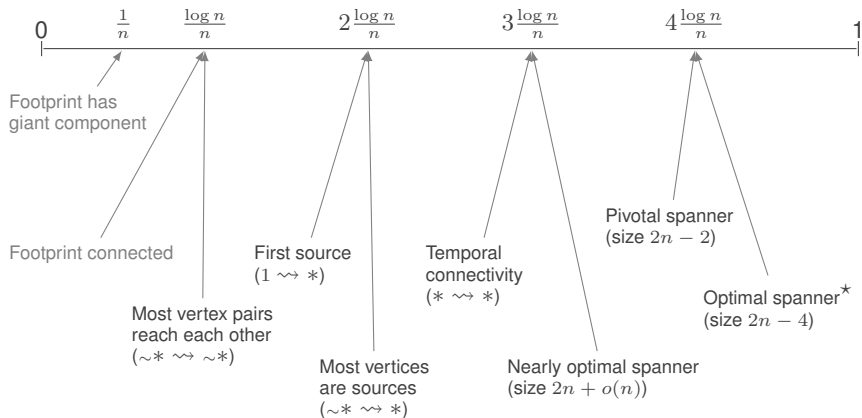
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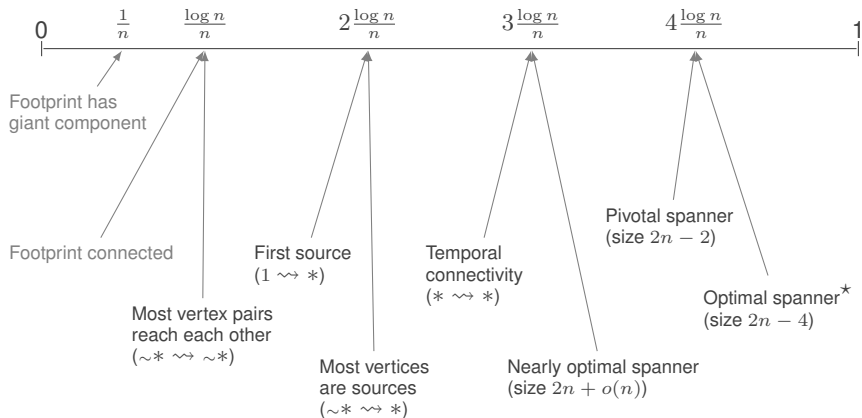
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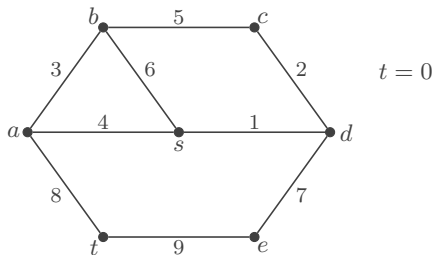
All the thresholds are sharp, except  $\star$  (open problem)

(sharp:  $\exists \epsilon(n) = o(1)$ , not true at  $(1 - \epsilon(n))p$ , true at  $(1 + \epsilon(n))p$ )

## Main technical tool: growth of a foremost tree

### Foremost tree (from $s$ )

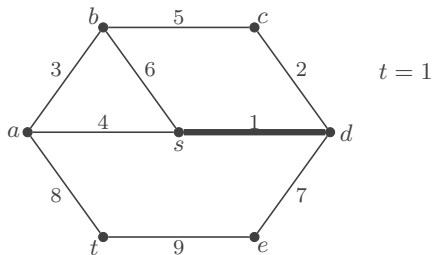
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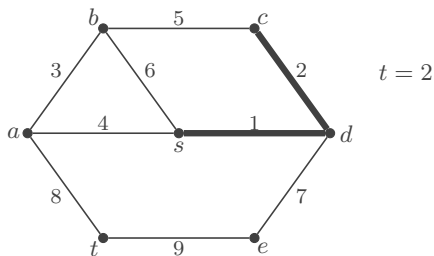
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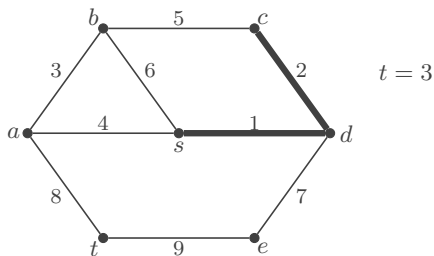
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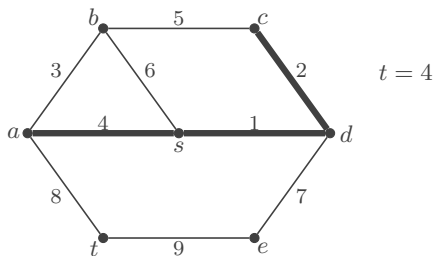
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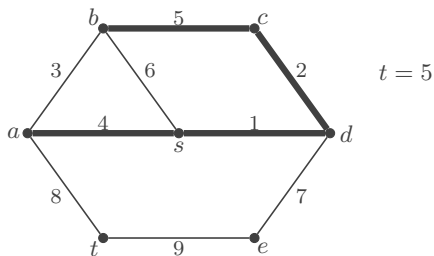




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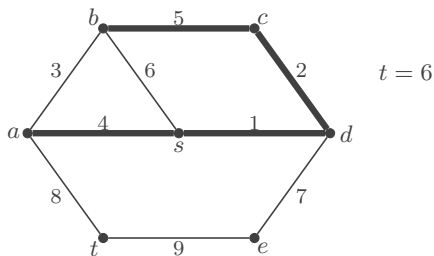
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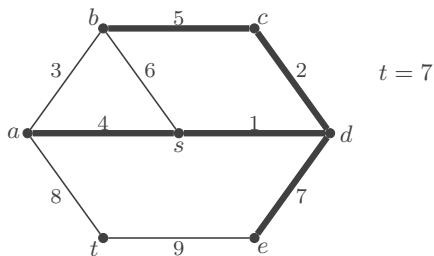
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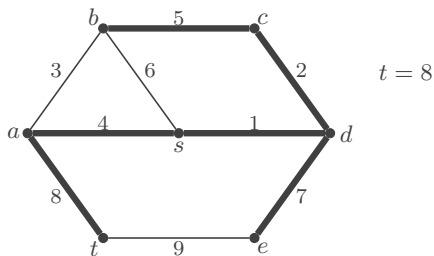
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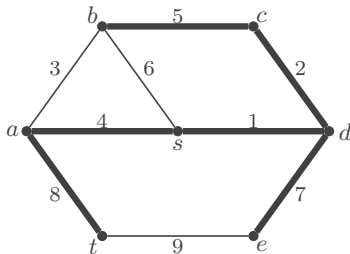
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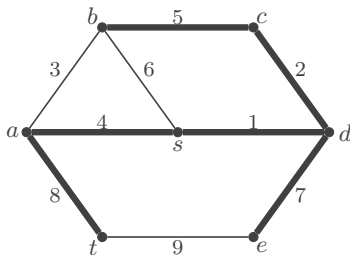


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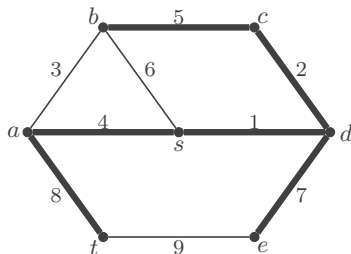
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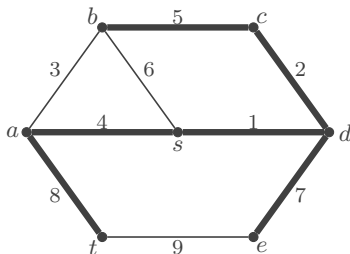
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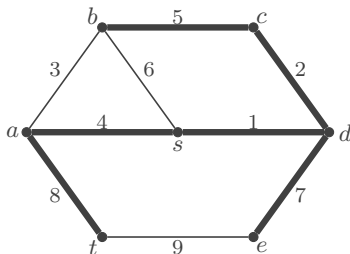
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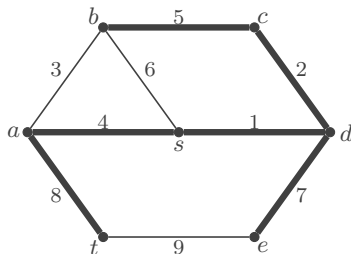
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- ▶ Azuma's inequality for concentration.

## Derived arguments

We note  $foremost(u)$  the set of vertices reached by a foremost tree from  $u$ .

### Reachability thresholds

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- ▶ Pivotal  $(* \rightsquigarrow 1 \rightsquigarrow^*) \longleftarrow (* \rightsquigarrow \sim^*) + (\sim^* \rightsquigarrow^*)$  ( $4 \log n/n$ )



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- ▶  $* \rightsquigarrow^* \iff a.a.s. \forall u, \forall v, v \in foremost(u)$  ( $3 \log n/n$ )

LB:  $(* \rightsquigarrow 1) + (\log n/n)$ , each non sink must have at least one new edge.

UB:  $(* \rightsquigarrow \sim^*) + (\log n/n)$ , each non sink is reached from at least one sink.

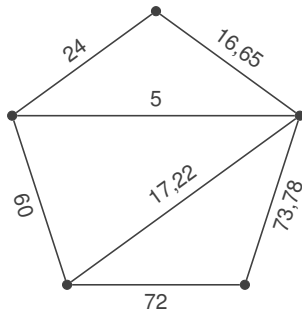
### Spanners

- ▶ Pivotal  $(* \rightsquigarrow 1 \rightsquigarrow^*) \longleftarrow (* \rightsquigarrow \sim^*) + (\sim^* \rightsquigarrow^*)$  ( $4 \log n/n$ )
- ▶ Optimal spanner (size  $2n - 4$ ) ( $4 \log n/n$ )  
Pivotal square. Sharp ?



# Random Non-Simple Temporal Graphs

$\mathcal{H}_{n,p}$ : Each edge independently appears according to a rate 1 Poisson process stopped at time  $p$ .



## Theorem

All our thresholds also hold for  $\mathcal{H}_{n,p}$ .

## Open questions (deterministic)

### Better spanners for temporal cliques

- ▶ Is  $O(n \log n)$  optimal for cliques? Is  $O(n)$  possible?

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	20	36 or 37	millions random instances

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Thank you!