# On Approximate Distance Labels and Routing Schemes with Affine Stretch 

Ittai Abraham - Cyril Gavoille

Microsoft, Mountview - University of Bordeaux

> DISC '11 - Rome

September 2011

## Topic

Given a graph $G$ with $n$ nodes compute an efficient data structure supporting approximate distance and/or routing queries in $G$.

- Efficient: fast pre-processing and low query time
- Approximate: guarantees on the distance $\hat{d}$ or route length returned w.r.t. the shortest path in $G$.

$$
\text { Ex: } \quad d_{G}(u, v) \leqslant \hat{d}(u, v) \leqslant f\left(d_{G}(u, v)\right)
$$

Affine stretch if $f(d)=\alpha \cdot d+\beta$

## Goals

- data structures of $o\left(n^{2}\right)$ space
- constant time query
- polynomial time pre-processing
- distributed data structure: split into $n$ balanced labels



## State-of-the-art

Thorup-Zwick distance oracle (J.ACM '05) Every weighted graph has a stretch $(2 k-1) d$ distance oracle of size $\tilde{O}\left(n^{1+1 / k}\right)$ with query time $O(k)$, and polynomial pre-processing. Moreover, the oracle can be represented as a distance labeling.

For $\mathbf{k}=2$ :
$\Rightarrow$ stretch $3 d$, space $n^{3 / 2}$, constant query time

## Can we do better for unweighted graphs?

Pǎtrașcu-Roditty (FOCS '10) Every unweighted graph has stretch $2 d+1$ distance oracle of size $\tilde{O}\left(n^{5 / 3}\right)$ with constant query time. (Label approach fails because of use a global hash table of size $n^{5 / 3}$ )

## Can we do better for unweighted graphs?

Pǎtrașcu-Roditty (FOCS '10) Every unweighted graph has stretch $2 d+1$ distance oracle of size $\tilde{O}\left(n^{5 / 3}\right)$ with constant query time. (Label approach fails because of use a global hash table of size $n^{5 / 3}$ )

## Theorem (1st contribution) <br> Let $k \geqslant 2$. Every unweighted graph has stretch $(2 k-2) d+1$ distance oracle of size $\tilde{O}\left(n^{1+2 /(2 k-1)}\right)$ with query time $O(k)$. Moreover it can be represented as a distance labeling.

For $\mathrm{k}=2$ :
$\Rightarrow$ stretch $2 d+1$, space $n^{1+2 / 3}=n^{5 / 3}$, constant query time

## Different trade-offs



## Different trade-offs

## [TZ05][PR10]



## Different trade-offs

## [TZ05][PR10][us]



## Different trade-offs

[TZ05][PR10][us]


The Best Solution depends on the question:

## Different trade-offs

## [TZ05][PR10][us]



The Best Solution depends on the question:
(1) What's the lowest space complexity with stretch $\leqslant 3 d$ ?

$$
\Rightarrow n^{3 / 2}[\text { TZO5] }
$$

## Different trade-offs

[TZ05][PR10][us]


The Best Solution depends on the question:
(1) What's the lowest space complexity with stretch $\leqslant 3 d$ ?
$\Rightarrow n^{3 / 2}$ [TZO5]
(2) What is the smallest stretch with space complexity $o\left(n^{2}\right)$ ?
$\Rightarrow$ at most $2 d+1$ [PR10][us]

## Proof for $k=2$

(we want $n$ labels of $\tilde{O}\left(n^{2 / 3}\right)$ bits and stretch $2 d+1$ )

## Proof for $k=2$

(we want $n$ labels of $\tilde{O}\left(n^{2 / 3}\right)$ bits and stretch $2 d+1$ )

Definitions: Given a set of landmarks $L \subset V$ :
$B_{L}(u)=\{v \in V: d(u, v)<d(u, L)\}$



## Proof for $k=2$

(we want $n$ labels of $\tilde{O}\left(n^{2 / 3}\right)$ bits and stretch $2 d+1$ )

Definitions: Given a set of landmarks $L \subset V$ :
$B_{L}(u)=\{v \in V: d(u, v)<d(u, L)\}$
$C_{L}(v)=\{u \in V: d(u, v)<d(u, L)\}$


## Proof for $k=2$

 (we want $n$ labels of $\tilde{O}\left(n^{2 / 3}\right)$ bits and stretch $2 d+1$ )Definitions: Given a set of landmarks $L \subset V$ :

$$
\begin{array}{ll}
B_{L}(u)=\{v \in V: d(u, v)<d(u, L)\} & \Rightarrow u \in C_{L}(v) \\
C_{L}(v)=\{u \in V: d(u, v)<d(u, L)\} & \Rightarrow v \in B_{L}(u)
\end{array}
$$



## Choosing the Landmarks

(Sampling Lemma from TZ [SPAA '01])

Select $L$ such that
(1) $|L| \sim n^{2 / 3}$
(2) $\forall u,\left|B_{L}(u)\right| \&\left|C_{L}(u)\right| \sim n^{1 / 3}$

## Storage

$$
S(u):=L \cup B_{L}(u) \cup\left(\bigcup_{v \in B_{L}(u)} C_{L}(v)\right)
$$

Storage for $u: S(u)$ and the distance from $u$ to every $v \in S(u)$, plus its closest landmarks $l_{v}$.
$\left[|S(u)|=\tilde{O}\left(n^{2 / 3}\right)\right.$, storage $\boldsymbol{V}$ ]

## Querying between $s$ and $t$


$\bullet$

If $t \in S(s)$, then returns $d(s, t)$

## Querying between $s$ and $t$



If $t \in S(s)$, then returns $d(s, t)$

## Querying between $s$ and $t$



If $t \in S(s)$, then returns $d(s, t)$
else returns $\left.\min \left\{d\left(s, l_{s}\right)+d\left(l_{s}\right), t\right), d\left(t, l_{t}\right)+d\left(l_{t}, t\right)\right\}$

## Querying between $s$ and $t$



If $t \in S(s)$, then returns $d(s, t)$
else returns $\left.\min \left\{d\left(s, l_{s}\right)+d\left(l_{s}\right), t\right), d\left(t, l_{t}\right)+d\left(l_{t}, t\right)\right\}$
[dictionary and 2-level hash table, query time $\boldsymbol{V}$ ]

## Querying between $s$ and $t$



If $t \in S(s)$, then returns $d(s, t)$
else returns $\left.\min \left\{d\left(s, l_{s}\right)+d\left(l_{s}\right), t\right), d\left(t, l_{t}\right)+d\left(l_{t}, t\right)\right\}$
[stretch $2 d+1$ ?]
If $t \notin S(s)$, then $B_{L}(s) \cap B_{L}(t)=\varnothing$ [otherwise $\exists w \in B_{L}(t) \cap B_{L}(s) \Rightarrow t \in C_{L}(w)$ and $\left.w \in B_{L}(s) \Rightarrow t \in S(s)\right]$

If $t \notin S(s)$, i.e., $B_{L}(s) \cap B_{L}(t)=\varnothing$ W.I.o.g. $d\left(s, l_{s}\right) \leqslant d\left(t, l_{t}\right)$


If $t \notin S(s)$, i.e., $B_{L}(s) \cap B_{L}(t)=\varnothing$ W.I.o.g. $d\left(s, l_{s}\right) \leqslant d\left(t, l_{t}\right)$


$$
\operatorname{I\sim }\left[d\left(s, l_{s}\right)-1\right]+1+\left[d\left(t, l_{t}\right)-1\right] \leqslant d
$$

If $t \notin S(s)$, i.e., $B_{L}(s) \cap B_{L}(t)=\varnothing$ W.I.o.g. $d\left(s, l_{s}\right) \leqslant d\left(t, l_{t}\right)$


$$
\operatorname{I\sim }\left[d\left(s, l_{s}\right)-1\right]+1+\left[d\left(t, l_{t}\right)-1\right] \leqslant d
$$

$$
\Rightarrow 2 d\left(s, l_{s}\right) \leqslant d+1
$$

If $t \notin S(s)$, i.e., $B_{L}(s) \cap B_{L}(t)=\varnothing$ W.I.o.g. $d\left(s, l_{s}\right) \leqslant d\left(t, l_{t}\right)$


$$
\left[d\left(s, l_{s}\right)-1\right]+1+\left[d\left(t, l_{t}\right)-1\right] \leqslant d
$$

$$
\Rightarrow 2 d\left(s, l_{s}\right) \leqslant d+1
$$

$$
\Rightarrow \hat{d} \leqslant 2 d\left(s, l_{s}\right)+d \leqslant 2 d+1
$$

## Observation

Routing with $n^{2 / 3}$-bit routing tables, polylog addresses and stretch $<3 d$ is not known. Routing query is not symetric!


The route $l_{s} \rightarrow t$ is space consuming: either $l_{s}$ 's table or $t$ 's address is large.

## What about Compact Routing?

Best routing scheme [Thorup-Zwick (SPAA '01)] achieves stretch $(4 k-5) d$ and routing tables of size $\tilde{O}\left(n^{1 / k}\right)$.
[TZ01]


## What about Compact Routing?

Best routing scheme [Thorup-Zwick (SPAA '01)] achieves stretch $(4 k-5) d$ and routing tables of size $O\left(n^{1 / k}\right)$.
[TZ01][us]


## Theorem (2nd contribution)

Let $k \geqslant 2$. Every unweighted graph has a routing scheme with tables of size $\tilde{O}\left(n^{3 /(3 k-2)}\right)$, stretch $(4 k-6) d+1$, and polylog addresses.

## Conclusion

Not clear if same space-stretch trade-offs can be achieved for both problems, even for $k=2$.

|  | stretch | size |
| :--- | :--- | :---: |
| Distance Labeling | $2 d+1$ | $\tilde{O}\left(n^{2 / 3}\right)$ |
| Compact Routing | $2 d+1$ | $\tilde{O}\left(n^{3 / 4}\right)$ |
|  | $d+O(1)$ | $\tilde{\Omega}(n)$ |

## Conclusion

Not clear if same space-stretch trade-offs can be achieved for both problems, even for $k=2$.

|  | stretch | size |
| :--- | :--- | :---: |
| Distance Labeling | $2 d+1$ | $\tilde{O}\left(n^{2 / 3}\right)$ |
| Compact Routing | $2 d+1$ | $\tilde{O}\left(n^{3 / 4}\right)$ |
|  | $d+O(1)$ | $\tilde{\Omega}(n)$ |

## Thank You!

