On Approximate Distance Labels and Routing Schemes with Affine Stretch

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Topic

Given a graph G with n nodes compute an **efficient** data structure supporting **approximate** distance and/or routing queries in G.

- Efficient: fast pre-processing and low query time
- **Approximate**: guarantees on the distance \hat{d} or route length returned w.r.t. the shortest path in *G*.

Ex: $d_G(u, v) \leqslant \hat{d}(u, v) \leqslant f(d_G(u, v))$

Affine stretch if $f(d) = \alpha \cdot d + \beta$

Goals

- data structures of $o(n^2)$ space
- constant time query
- polynomial time pre-processing
- distributed data structure: split into n balanced labels



Thorup-Zwick distance oracle (J.ACM '05) Every weighted graph has a stretch (2k-1)d distance oracle of size $\tilde{O}(n^{1+1/k})$ with query time O(k), and polynomial pre-processing. Moreover, the oracle can be represented as a distance labeling.

For k=2:

 \Rightarrow stretch 3d, space $n^{3/2}$, constant query time

Can we do better for unweighted graphs?

Pătrașcu-Roditty (FOCS '10) Every unweighted graph has stretch 2d + 1 distance oracle of size $\tilde{O}(n^{5/3})$ with constant query time. (Label approach fails because of use a global hash table of size $n^{5/3}$)

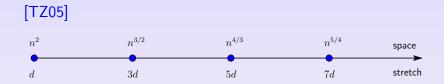
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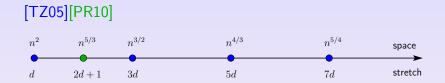
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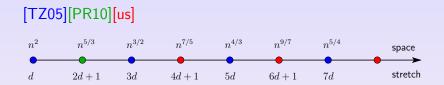
Theorem (1st contribution)

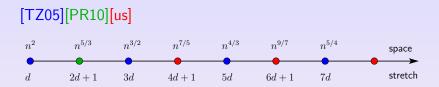
Let $k \ge 2$. Every unweighted graph has stretch (2k-2)d+1distance oracle of size $\tilde{O}(n^{1+2/(2k-1)})$ with query time O(k). Moreover it can be represented as a distance labeling.

For k=2: \Rightarrow stretch 2d + 1, space $n^{1+2/3} = n^{5/3}$, constant query time

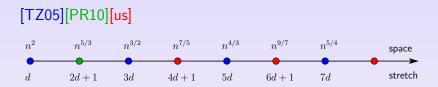






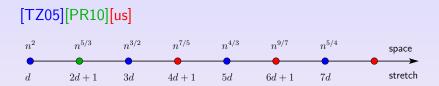


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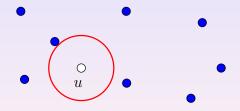
• What's the lowest space complexity with stretch $\leq 3d?$ $\Rightarrow n^{3/2}$ [TZ05]



The Best Solution depends on the question:

- What's the lowest space complexity with stretch $\leqslant 3d?$ $\Rightarrow n^{3/2} \ [{\rm TZ05}]$
- ② What is the smallest stretch with space complexity $o(n^2)$? ⇒ at most 2d + 1 [PR10][us]

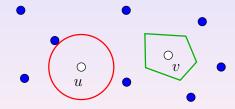
Definitions: Given a set of landmarks $L \subset V$: $B_L(u) = \{v \in V : d(u, v) < d(u, L)\}$



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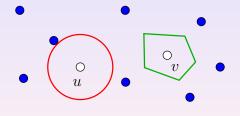
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Definitions: Given a set of landmarks $L \subset V$:

$$B_L(u) = \{ v \in V : d(u, v) < d(u, L) \} \Rightarrow u \in C_L(v)$$

$$C_L(v) = \{ u \in V : d(u, v) < d(u, L) \} \Rightarrow v \in B_L(u)$$



 $\mathbb{R} \quad v \in B_L(u) \text{ iff } u \in C_L(v)$

Choosing the Landmarks (Sampling Lemma from TZ [SPAA '01])

Select L such that

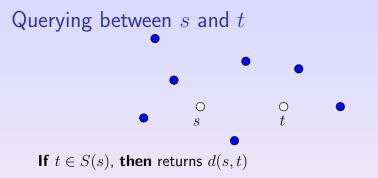
- **1** $|L| \sim n^{2/3}$
- **2** $\forall u, |B_L(u)| \& |C_L(u)| \sim n^{1/3}$

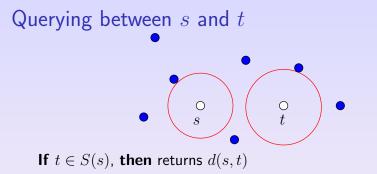
$S(u) := L \cup B_L(u) \cup \left(\bigcup_{v \in B_L(u)} C_L(v)\right)$

Storage for u: S(u) and the distance from u to every $v \in S(u)$, plus its closest landmarks l_v .

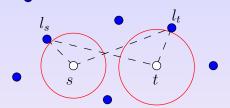
 $[\ |S(u)| = \tilde{O}(n^{2/3}) \text{, storage } \checkmark]$

Storage



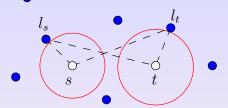


Querying between s and t



If $t \in S(s)$, then returns d(s,t)else returns $\min \{d(s,l_s) + d(l_s),t), d(t,l_t) + d(l_t,t)\}$

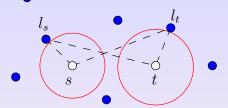
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[dictionary and 2-level hash table, query time ✔]

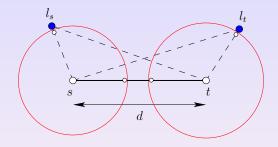
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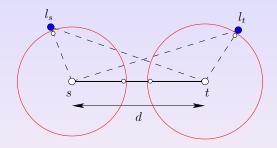


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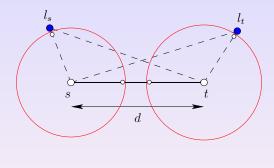
[stretch 2d + 1?]

If $t \notin S(s)$, then $B_L(s) \cap B_L(t) = \emptyset$ [otherwise $\exists w \in B_L(t) \cap B_L(s) \Rightarrow t \in C_L(w)$ and $w \in B_L(s) \Rightarrow t \in S(s)$]



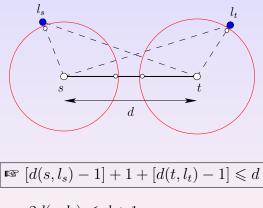


$$\operatorname{res}\left[d(s,l_s)-1\right]+1+\left[d(t,l_t)-1\right]\leqslant d$$



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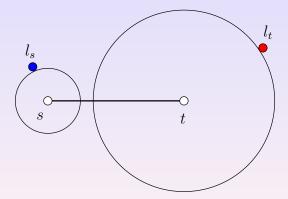
$$\Rightarrow 2d(s, l_s) \leqslant d+1$$



 $\Rightarrow 2d(s, l_s) \leqslant d + 1$ $\Rightarrow \hat{d} \leqslant 2d(s, l_s) + d \leqslant 2d + 1$

Observation

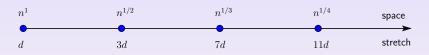
Routing with $n^{2/3}$ -bit routing tables, **polylog** addresses and stretch < 3d is not known. Routing query is not symetric!



The route $l_s \rightarrow t$ is space consuming: either l_s 's table or t's address is large.

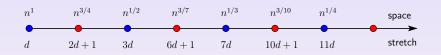
What about Compact Routing?

Best routing scheme [Thorup-Zwick (SPAA '01)] achieves stretch (4k-5)d and routing tables of size $\tilde{O}(n^{1/k})$. [TZ01]



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Theorem (2nd contribution)

Let $k \ge 2$. Every unweighted graph has a routing scheme with tables of size $\tilde{O}(n^{3/(3k-2)})$, stretch (4k-6)d+1, and polylog addresses.

Conclusion

Not clear if same space-stretch trade-offs can be achieved for both problems, even for k = 2.

	stretch	size
Distance Labeling	2d + 1	$\tilde{O}(n^{2/3})$
Compact Routing	2d + 1	$\tilde{O}(n^{3/4})$
	d + O(1)	$\hat{ ilde{\Omega}}(n)$

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Thank You!