

Advanced Algorithmics and Artificial Intelligence

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Objectives

- Deepen your understanding of programs
- Provide knowledge of widely-used algorithms
- Give some insight into theoretical issues of Computer Science

- Mathematics: elementary analysis and linear algebra
- Programming practice in C and Java: loops, recursive functions, classes, generics
- Arrays: searching and sorting algorithms
- Data structures: strings, lists, stacks, queues, trees

- ① Design and Analysis of Algorithms
- ② Advanced Data Structures
- ③ Graph Algorithms
- ④ AI

Lectures

- Olivier Baudon, UB
- olivier.baudon@labri.fr
- 10 × 2h - lectures

Lectures

- Olivier Baudon, UB
- olivier.baudon@labri.fr
- $10 \times 2\text{h}$ - lectures

Training

- Quan Thanh Tho, HCMUT
- qttho@cse.hcmut.edu.vn
- $9 \times 3\text{h}$ -training sessions

Lectures

- Olivier Baudon, UB
- olivier.baudon@labri.fr
- $10 \times 2\text{h}$ - lectures
- 3h final exam (2/3)

Training

- Quan Thanh Tho, HCMUT
- qttho@cse.hcmut.edu.vn
- $9 \times 3\text{h}$ -training sessions
- exams and/or projects (1/3)

Bibliography

-  T. J. Cormen, C. E. Leiserson, R. L. Rivest, and C. Stein.
Introduction to Algorithms.
The MIT Press, third edition, 2009.
-  Shimon Even.
Graph Algorithms.
Computer Science Press, 1979.
-  S. Russel and P. Norvig.
Artificial Intelligence, a modern approach.
Prentice Hall Ed, 2009.

Schedule

- Design and Analysis of Algorithms
- Data Structures
- Graph Algorithms
- AI

- Elementary Analysis

- Elementary Analysis
 - Classification of Algorithms
 - Design Methods
 - Analysis of Algorithms

- **Problem types**

computing, sorting, searching, optimization...

- **Data types**

numbers, strings, lists, trees, graphs...

- **Implementation**

iterative algorithms, recursive algorithms...

- **Design methods**

divide-and-conquer, dynamic programming, greedy algorithms...

- Elementary Analysis

- Classification of Algorithms
- Design Methods
- Analysis of Algorithms

Divide-and-Conquer: Dichotomic Search

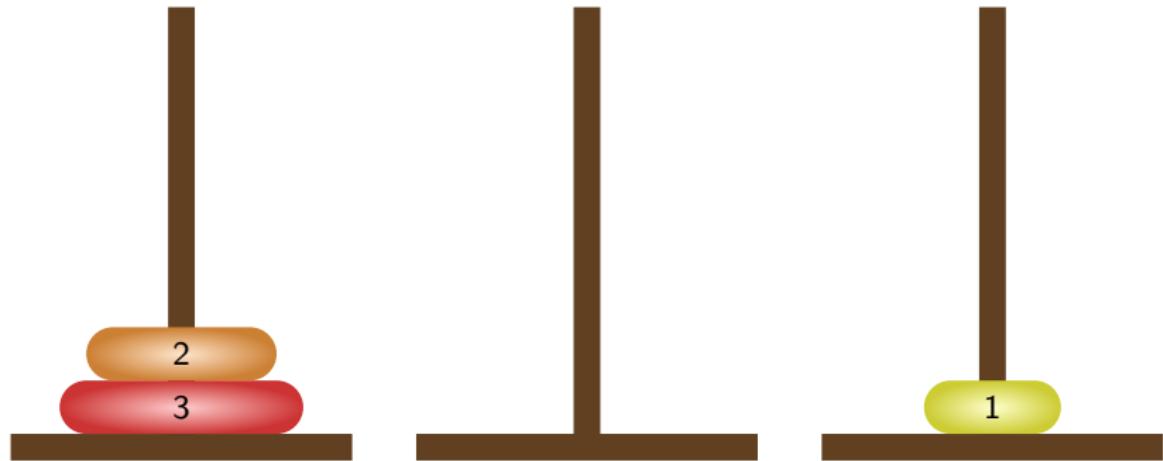
```
int search(int x, sortedArray A of size n) {
    int start = 0, end = n-1, middle;
    while (start <= end) {
        middle = (start + end)/2;
        if (x == A[middle])
            return FOUND ;
        if (x < A[middle])
            end = middle - 1; // restrict to lower half
        else
            start = middle + 1; // restrict to upper half
    }
    return NOT_FOUND ;
}
```

Divide-and-conquer: The Towers of Hanoi



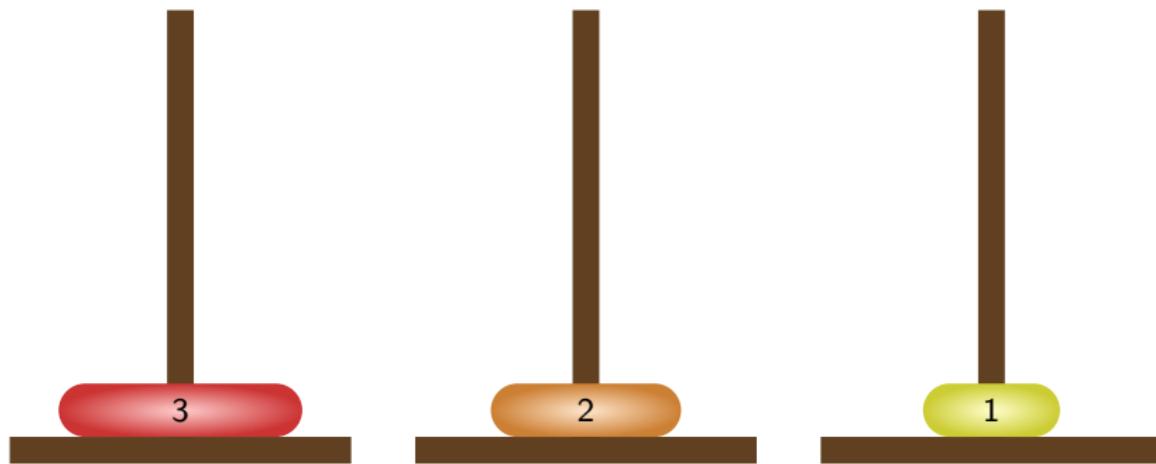
Authors: Martin Hofmann and Berteun Damman

Divide-and-conquer: The Towers of Hanoi



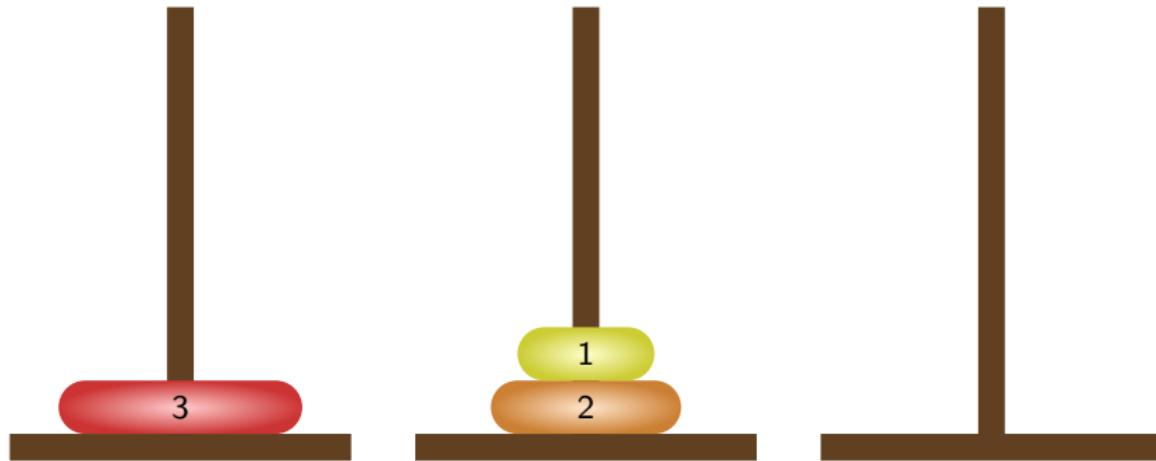
Moved disc from pole 1 to pole 3.

Divide-and-conquer: The Towers of Hanoi



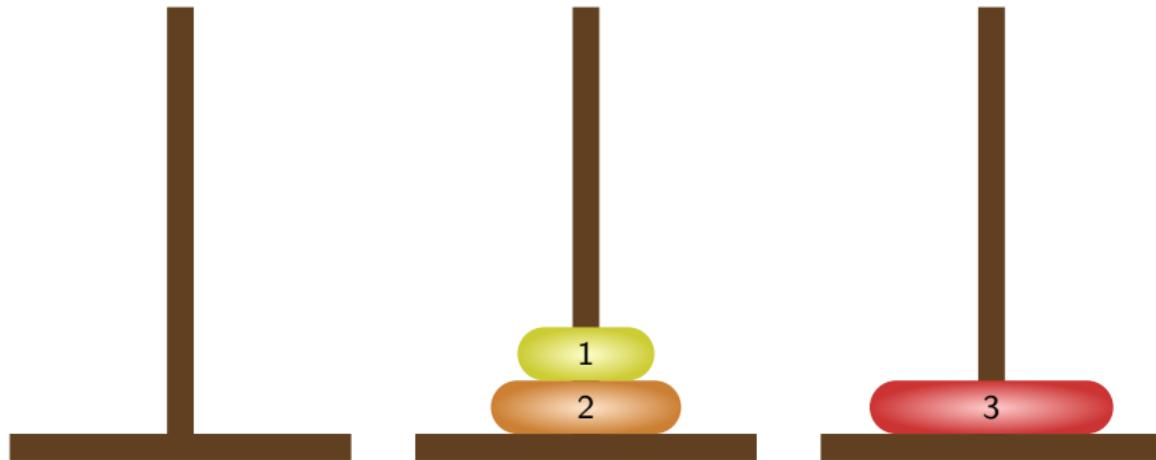
Moved disc from pole 1 to pole 2.

Divide-and-conquer: The Towers of Hanoi



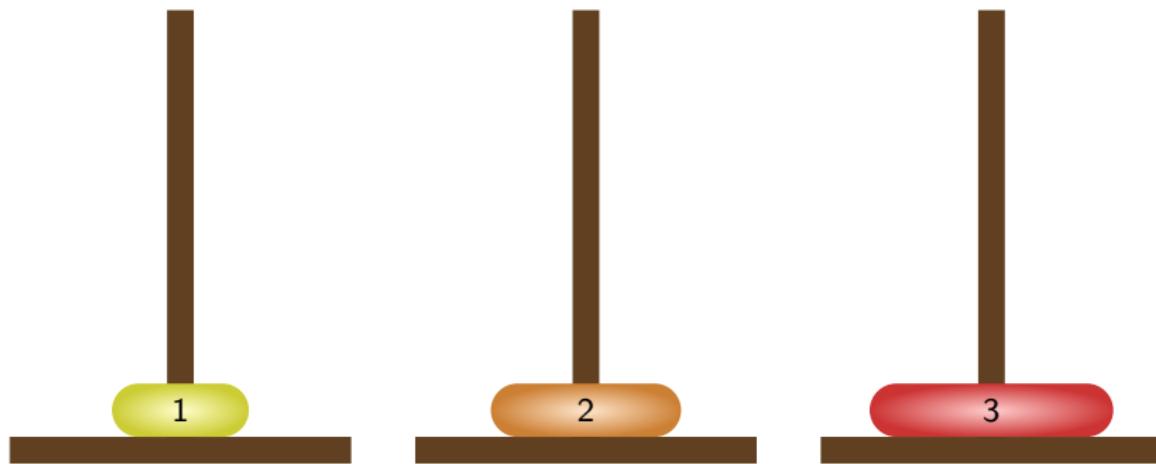
Moved disc from pole 3 to pole 2.

Divide-and-conquer: The Towers of Hanoi



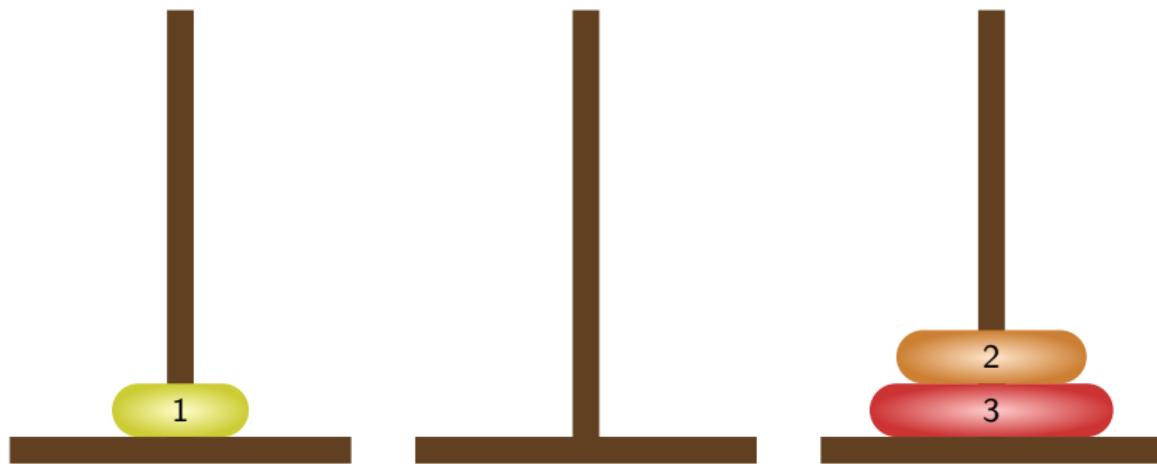
Moved disc from pole 1 to pole 3.

Divide-and-conquer: The Towers of Hanoi



Moved disc from pole 2 to pole 1.

Divide-and-conquer: The Towers of Hanoi



Moved disc from pole 2 to pole 3.

Divide-and-conquer: The Towers of Hanoi



Moved disc from pole 1 to pole 3.

Divide-and-conquer: The Towers of Hanoi

```
void hanoi(int n,int from,int to,int other) {  
    if (n > 1)  
        hanoi(n-1,from,other,to);  
  
    printf("Move disc from pole %d to pole %d.\n",from,to);  
  
    if (n > 1)  
        hanoi(n-1,other,to,from);  
}
```

Divide-and-Conquer: MergeSort

```
sort array A of size n:  
  if (n ≥ 2) {  
    sort the first half of A;  
    sort the second half of A;  
    merge the two sorted halves;  
  }
```

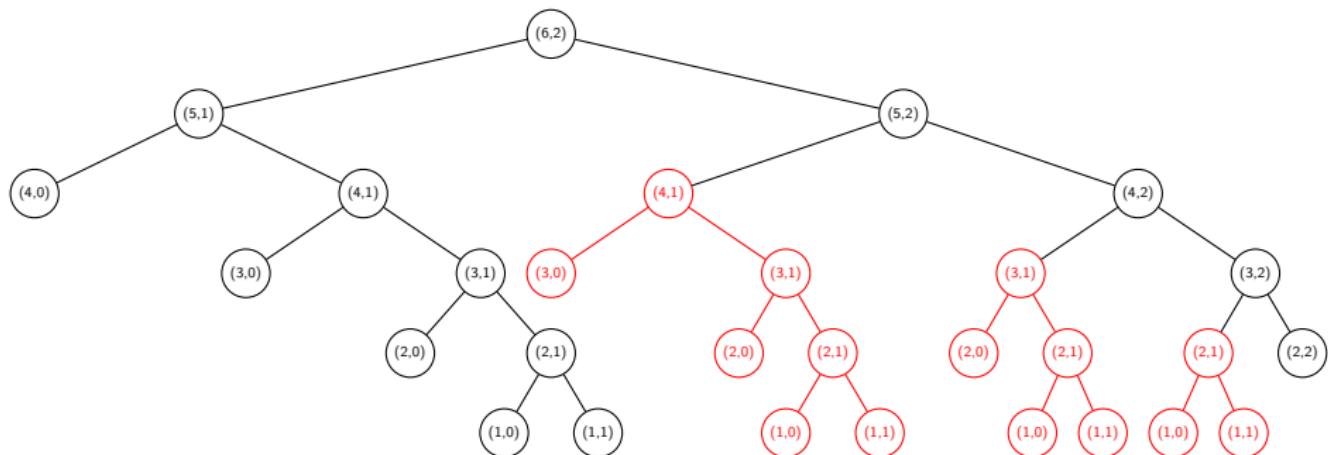
Binomial Coefficients

$n \setminus p$	0	1	2	3	4	5	6
1	1	1					
2	1	2	1				
3	1	3	3	1			
4	1	4	6	4	1		
5	1	5	10	10	5	1	
6	1	6	15	20	15	6	1

$$\text{binomial}(n, p) = \text{binomial}(n-1, p-1) + \text{binomial}(n-1, p)$$

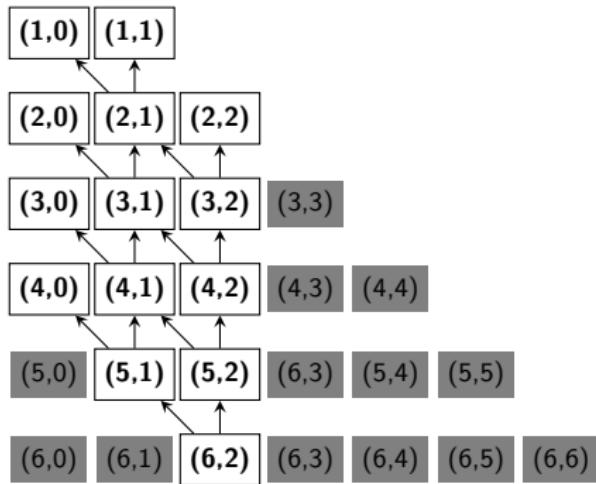
Recursive Computation of Binomial Coefficients

```
int binomial(int n, int p) {  
    if (p == 0 || p == n)  
        return 1;  
    return binomial(n-1, p-1) + binomial(n-1, p);  
}
```

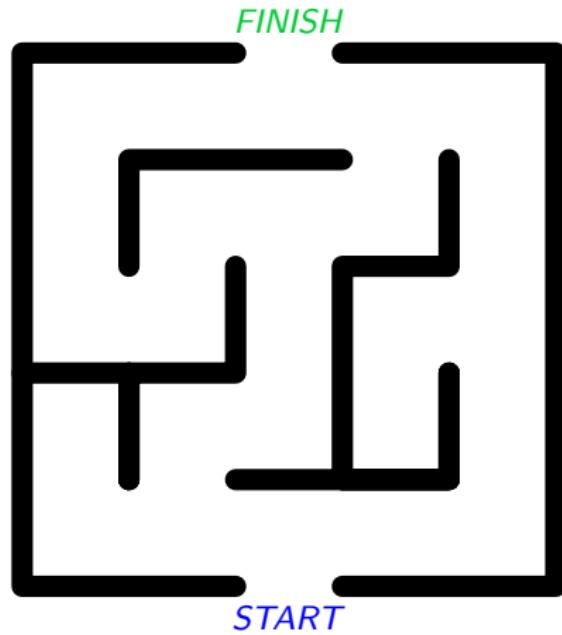


Dynamic Programming: Binomial Coefficients

```
int binomial(int n, int p) {  
    if (table[n][p] > 0)  
        return table[n][p];  
    if (p == 0 || p == n)  
        return table[n][p] = 1;  
    return table[n][p] = binomial(n-1, p-1) + binomial(n-1, p);  
}
```

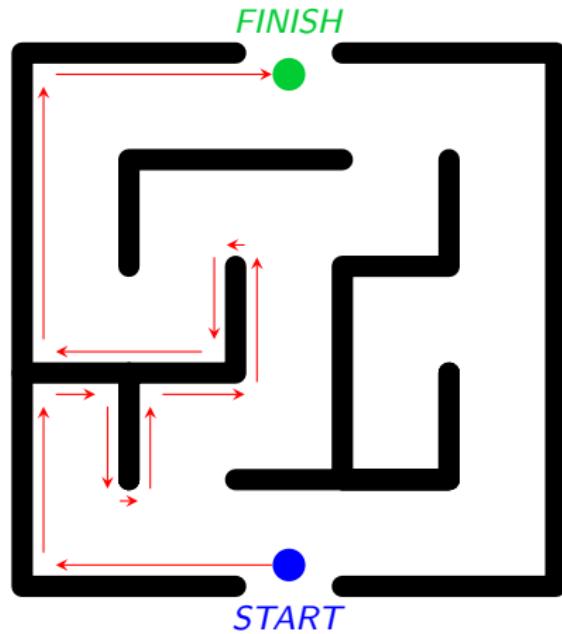


Greedy Algorithms: Maze



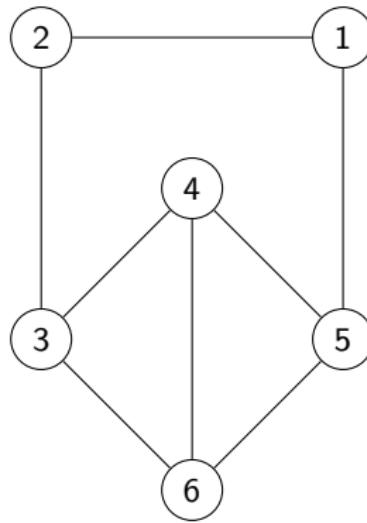
Algorithm: follow the wall on your left.

Greedy Algorithms: Maze



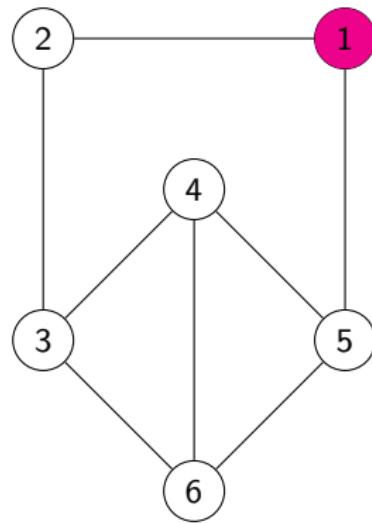
Algorithm: follow the wall on your left.

Greedy Algorithms: Graph Colouring



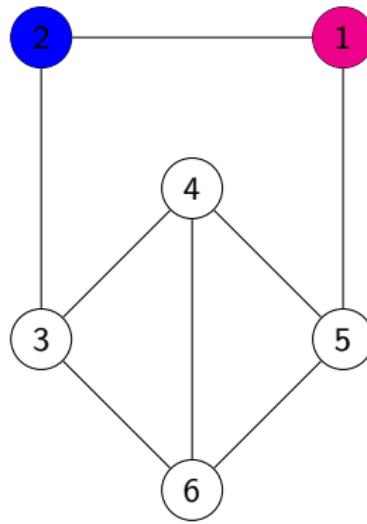
Algorithm: colour each node with the first available colour.

Greedy Algorithms: Graph Colouring



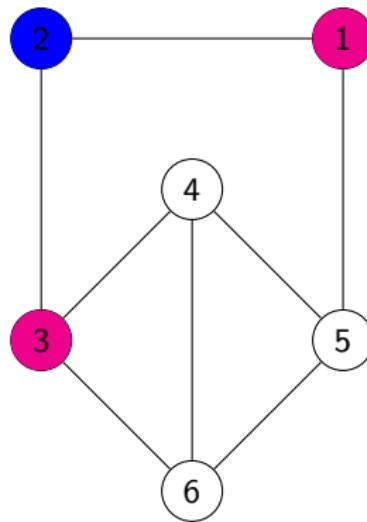
Algorithm: colour each node with the first available colour.

Greedy Algorithms: Graph Colouring



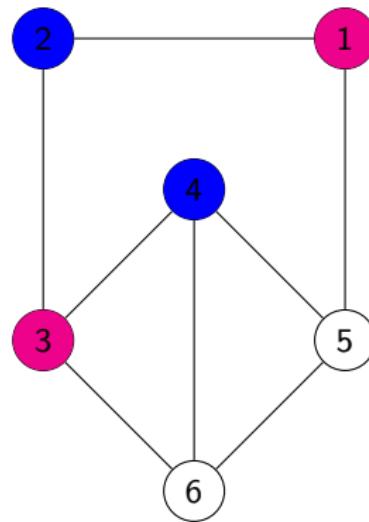
Algorithm: colour each node with the first available colour.

Greedy Algorithms: Graph Colouring



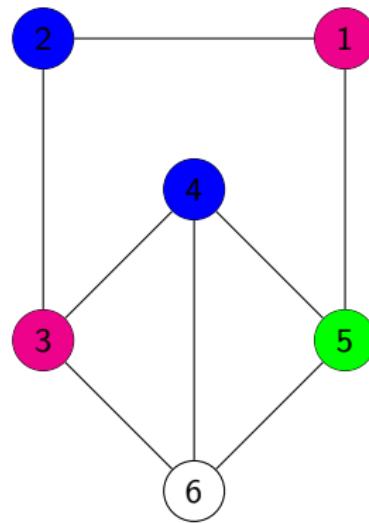
Algorithm: colour each node with the first available colour.

Greedy Algorithms: Graph Colouring



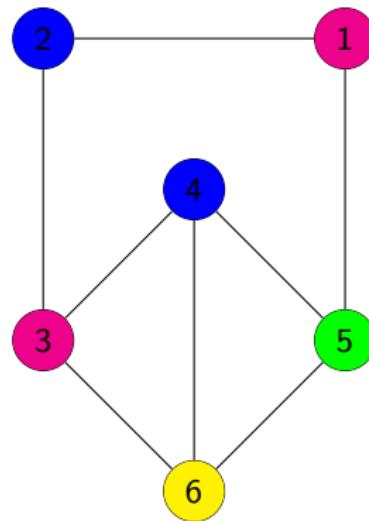
Algorithm: colour each node with the first available colour.

Greedy Algorithms: Graph Colouring



Algorithm: colour each node with the first available colour.

Greedy Algorithms: Graph Colouring



Algorithm: colour each node with the first available colour.

- Elementary Analysis

- Classification of Algorithms
- Design Methods
- Analysis of Algorithms

A “good” algorithm should be

- effective
- efficient
- economic

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- effective → *prove correctness*
- efficient
- economic

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- effective → *prove correctness*
- efficient → *estimate run-time*
- economic

A “good” algorithm should be

- effective → *prove correctness*
- efficient → *estimate run-time*
- economic → *estimate memory needed,
but also cost of work and maintenance*

Proving Correctness: Dichotomic Search

```
int search(int x, sortedArray A of size n) {
    int start = 0, end = n-1, middle;
    while (start <= end) {
        middle = (start + end) / 2;
        if (x == A[middle])
            return FOUND ;
        if (x < A[middle])
            end = middle - 1; // restrict to lower half
        else
            start = middle + 1; // restrict to upper half
    }
    return NOT_FOUND ;
}
```

- **Termination**

"end - start" strictly decreases between successive executions of the while loop

- **Partial correctness follows from loop invariant**

- $A[i] < x$ if $i < start$
- $A[i] > x$ if $i > end$

```
sort array A of size n:  
  if (n ≥ 2) {  
    sort the first half of A;  
    sort the second half of A;  
    merge the two sorted halves;  
  }
```

- **Termination**

the size of the array to sort strictly decreases in the recursive calls

- **Partial correctness**

- if $n < 2$: obvious
- otherwise, can be deduced from the correctness of the recursive calls

Proving Correctness: The Towers of Hanoi

```
void hanoi(int n, int from, int to, int other) {  
    if (n > 1)  
        hanoi(n-1, from, other, to);  
  
    printf("Move disc from pole %d to pole %d.\n",from,to);  
  
    if (n > 1)  
        hanoi(n-1, other, to, from);  
}
```

- **Termination**

The argument n strictly decreases in the recursive calls.

- **Partial correctness**

- obvious if $n \leq 1$
- otherwise, can be deduced from the correctness of the recursive calls, slightly modifying the problem (poles may contain other discs)

Proving Correctness: Binomial Coefficients

```
int binomial(int n, int p) {
    if (table[n][p] > 0)
        return table[n][p];
    if (p == 0 || p == n)
        return table[n][p] = 1;
    return table[n][p] = binomial(n-1,p-1) + binomial(n-1,p);
}
```

- Termination

The sum $n+p$ of the arguments strictly decreases in the recursive calls.

- Partial correctness

We prove by induction that $\text{binomial}(n,p)$ returns $\binom{n}{p}$, and that at each step of the algorithm, if $\text{table}[i][j] > 0$, then $\text{table}[i][j]$ is equal to $\binom{i}{j}$

- obvious if $\text{table}[n][p] \neq 0$ and either $p = 0$ or $p = n$
- otherwise, can be deduced from the correctness of the recursive calls

Asymptotic Complexity: big O, Omega and Theta

T_n : run-time of an algorithm, depending on n : size of the input, is

- **$O(f(n))$** “big O”: asymptotic upper bound
if for some constant $c > 0$, $T_n \leq c \times f(n)$ when n is large enough
- **$\Omega(f(n))$** “Omega”: asymptotic lower bound
if for some constant $c > 0$, $T_n \geq c \times f(n)$ when n is large enough
- **$\Theta(f(n))$** “Theta”: asymptotic equivalent (up to a multiplying factor)
if T_n is both $O(f(n))$ and $\Omega(f(n))$

- **Linear:** $\Theta(n)$
- **Quadratic:** $\Theta(n^2)$
- **Logarithmic:** $\Theta(\log n)$
- **Polynomial:** $\Theta(n^k)$, for some $k > 0$
- **Exponential:** $\Theta(k^n)$, for some $k > 1$
- **Factorial:** $\Theta(n!)$

Common Asymptotic Behaviours: Figures

linear n	quadratic n^2	logarithmic $\lceil \log_2 n \rceil$	exponential 2^n	factorial $n!$
1	1	0	2	1
2	4	0	4	2
5	25	3	32	120
10	100	4	1,024	3,628,800
100	10,000	7	1.2×10^{30}	9.3×10^{157}
1,000	1,000,000	10	10^{301}	4×10^{2567}
10,000	100,000,000	14	1.9×10^{3010}	2.8×10^{35659}

Complexity of Iterative Algorithms: Dichotomic Search

```
int search(int x, sortedArray A of size n) {  
    int start = 0, end = n-1, middle;  
    while (start <= end) {  
        middle = (start + end)/2 ;  
        if (x == A[middle])  
            return FOUND;  
        if (x < A[middle])  
            end = middle - 1; // restrict to lower half  
        else  
            start = middle + 1; // restrict to upper half  
    }  
    return NOT_FOUND ;  
}
```

Complexity: $O(\log_2 n)$

(at most $\lceil \log_2 n \rceil$ executions of the `while` loop, and each execution is $O(1)$)

Complexity of Recursive Algorithms: Search

```
search element x in sorted array A of size n:  
    determine in which half x is to be searched for;  
    search x in this half;
```

$$T_n = c + T_{\frac{n}{2}} \text{ is } \mathbf{O}(\log_2 n)$$

```
search element x in unsorted array A of size n:  
    search x in the first half of A;  
    if (not found)  
        search x in the second half of A;
```

$$T_n = c + 2 \times T_{\frac{n}{2}} \text{ is } \mathbf{O}(n) \text{ but not } \mathbf{O}(\log_2 n)$$

Complexity of Recursive Algorithms: MergeSort

```
sort array A of size n:  
  if (n ≥ 2) {  
    sort the first half of A;  
    sort the second half of A;  
    merge the two sorted halves;  
  }
```

$$\begin{aligned}T_n &= 2 \times T_{\frac{n}{2}} + c \times n \\&= 2(2 \times T_{\frac{n}{4}} + c \times \frac{n}{2}) + c \times n \\&= \dots \\&= c \times \left(n + 2\frac{n}{2} + \dots + 2^k \frac{n}{2^k}\right) \text{ where } k = \log_2 n \\&= c \times n \times \log_2 n\end{aligned}$$

is $\Theta(n \log_2 n)$

Complexity of Recursive Algorithms: QuickSort

```
sort array A[first..last] {
    if (first >= last) return;
    pivot = A[first];
    i = first; j = last;
    while (i <= j) {
        if (A[j] > pivot) j--;
        else { swap(A[i],A[j]); i++; }
    }
    sort A[first..j];
    sort A[i..last];
}
```

- Worst case: $T_n = c \times n + T_{n-1} = c \times (n + (n - 1) + \dots + 1)$ is $\mathbf{O}(n^2)$
- Best case: $T_n = c \times n + 2T_{\frac{n}{2}}$ is $\mathbf{O}(n \log_2 n)$